

## SFL317 Electric feedback three-stage servo valve



### □ Features

- Spool position closed-loop control feedback through differential linear displacement transducer (LVDT)
- Integrated amplifier with polarity protection
- High resolution, low hysteresis, good zero stability
- Parameters are pre-set at the factory

### □ Main Parameter

#### General parameters

Operating medium	Mineral oil or other fluids according to DIN 51524		
Viscosity range	mm <sup>2</sup> /s	15 to 380 (30 to 45 recommended)	
Oil temperature range	°C	-20 to +80 (recommended +40 to +50)	
Storage temperature	°C	-20 to +80	
Operating ambient temperature	°C	-30 to +70	
Oil cleanliness	Maximum permissible degree of contamination of the oil, Class 6 per NAS 1638		
Filtration accuracy	Recommended filter minimum filtration ratio $\beta_{5\%} \geq 75$		
Seal material	Nitrile rubber, fluorine rubber, or other sealing materials according to user needs		
Installation Requirements	MOOG Compliant		
Weight	k g	23.2	

#### Technical Parameters

Work Pressure					
Ports P, A, B (inside X port)	MPa	≤ 31.5			
Ports P, A, B (X port drains)	MPa	≤ 35			
Port T (Y-port inner row)	MPa	≤ 21			
Port T (Y port drains)	MPa	≤ 35			
Rated flow (differential pressure $\Delta P = 7 \text{ MPa}$ ) L/min	400	630	800	1000	
Zero bias	%	≤ 2			
Hysteresis loop	%	≤ 0.5			
Resolution	%	≤ 0.2			
Non-linearity	%	≤ 10			
Asymmetry	%	≤ 10			
Endoleak	L/min	≤ 10	≤ 14	≤ 14	≤ 14
Amplitude bandwidth (-3dB)	Hz	≥ 100			
Phase bandwidth (-90°)	Hz	≥ 100			
Body structure	Three-Stage Servo Valve with Spool and Sleeve				
Pilot stage	Secondary nozzle flapper servo valve				
Pilot stage control oil form	Optional internal or external control				



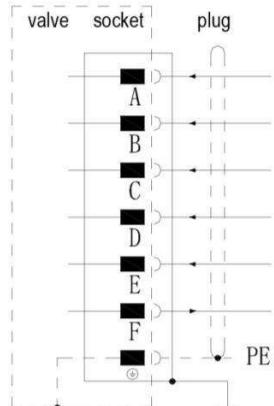
### Electrical Parameters

Valve protection class	Conforms to standards EN60 529, IP65
Instruction signal	0~±10mA; or 0~±10V; or 4~20mA
Supply power	24VDC (22~28VDC), I <sub>max</sub> =300mA, or ±15VDC, I <sub>max</sub> =250mA
Socket	6+PE
Command signal and spool displacement	The stroke of the spool is proportional to (UD - UE). When UD - UE=+10V, the spool is at the fully open position of P→A and B→T. When the command signal is 0V, the spool is in the neutral position; the stroke of the spool is proportional to At (ID= - IE), when ID=+10mA, the spool is in the fully open position of P→A, B→T, and the spool is in the neutral position when the command signal is 0mA
Main spool actual displacement output	IF - C=4~20mA, when the spool is in the neutral position, IF - C=12mA, when the valve port is fully open and P → B, A → T, IF - C=4mA, when the valve port is fully open and P → A, IF - C=20mA when B → T; or UF - C=2~10V, 6V when the spool is in the middle position; or 0~±10mA

Note: All signal lines must use shielded cables.

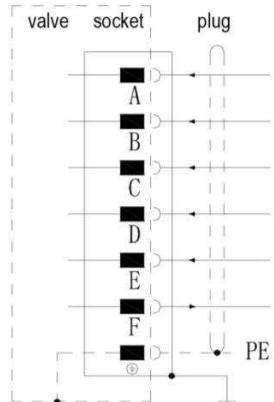
### □ Electrical Wiring

#### 24VDC



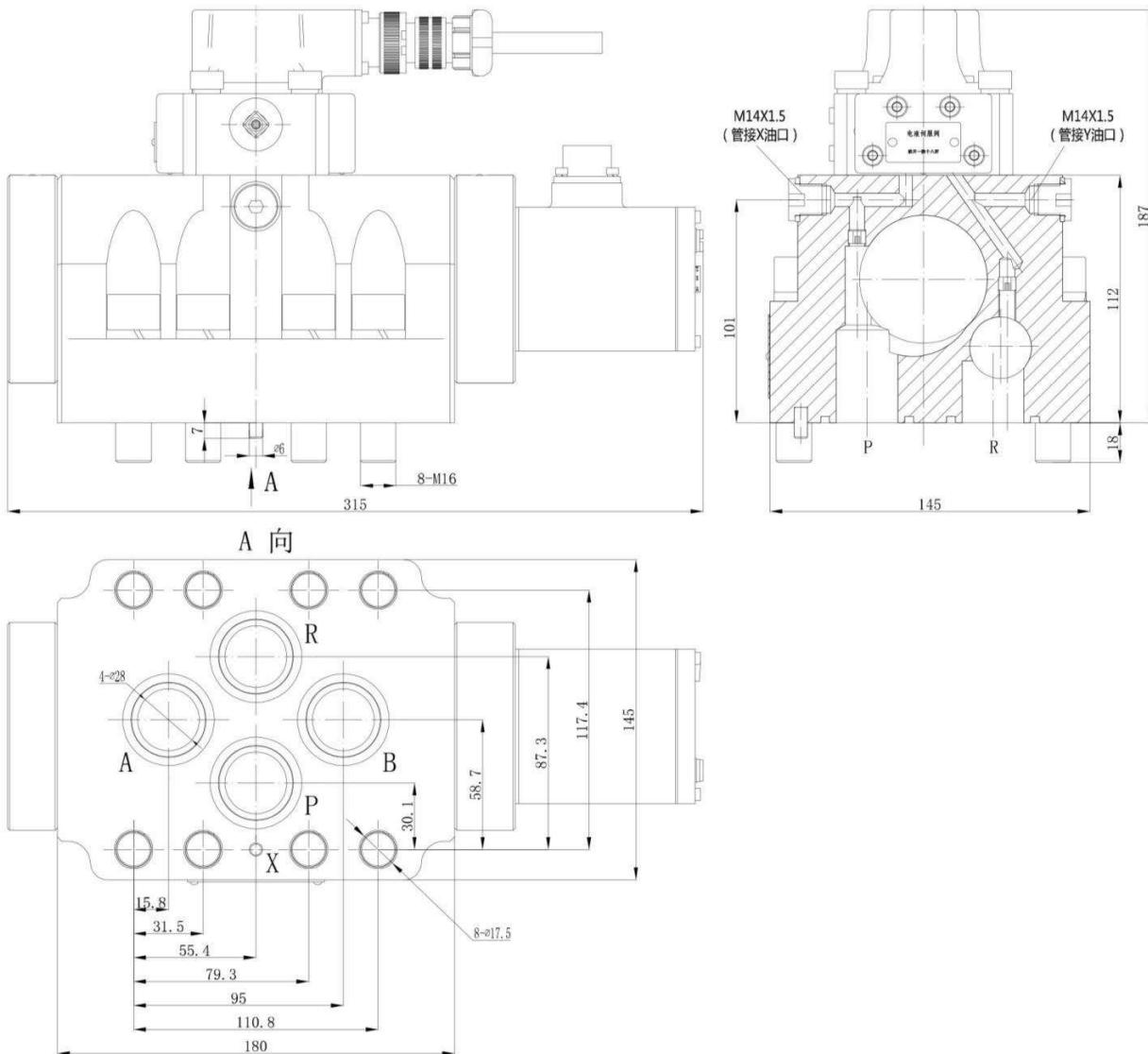
Function	Current instruction(0~±10mA)	Voltage command(0~±10VDC)
Power supply		24VDC (18~32VDC), I <sub>max</sub> =300mA
Power/signal ground		(0V)
enable signal Non-enable signal	U <sub>Cg</sub> >8.5VDC U <sub>Cg</sub> <6.5VDC	24VDC , I <sub>e</sub> =2.0mA
Instruction signal input (differential)	I <sub>b</sub> =-I <sub>a</sub> : 0~±10mA (Re=200 Ω ) I <sub>t</sub> =-I <sub>b</sub> : 0~±10mA (Re=200 Ω )	U <sub>b-a</sub> =0~+10V Re=10k Ω
Spool actual displacement output signal	I <sub>Fg</sub> =4~20mA, At 12mA, the main spool is in the middle position, and the load impedance is 100-500Ω	
Protective grounding		

#### ±15VDC



Function	Current instruction(0~±10mA)	Voltage command(0~±10VDC)
Power supply	+15VDC±3	
Power supply	-15VDC±3	
Power/signal ground	(0V)	
enable signal Non-enable signal	0~±10mA Load Resistance 1k Ω	0~±10V input resistance 10k Ω
Instruction signal input (differential)	I <sub>b</sub> =-I <sub>a</sub> : 0~±10mA (Re=200 Ω ) I <sub>t</sub> =-I <sub>b</sub> : 0~±10mA (Re=200 Ω )	U <sub>b-a</sub> =0~±10V , Re=10k Ω
Spool actual displacement output signal	0~±10mA, Load resistance max 500Ω	0~±10VDC, input resistance 50kΩ
Protective grounding		

**Dimensions and Interface**



- The roughness of the installation surface of the valve is not less than  $\frac{1.6}{\mu}$ , and the flatness is less than 0.01mm.
- In order to ensure that the servo valve can work normally, the system must be flushed before trial operation.

**Spare Parts & Accessories**

Parts or accessories	Size or Specifications	Quantity
NBR O-rings For P, T, A and B ports	35.5×3.55	4
Configuration plug (degree of protection IP65)	6+PE plug	1
Mounting screws	M16×75	8
Protective base	PP or 2A12	1



**□ Ordering Information**

SFL317 -



**Rated flow**

When  $P_n=3.5\text{ MPa}$  per section  $Q_n[\text{L/min}]$

40	400
63	630
80	800
99	1000

**Maximum Working Pressure and Body Material**

K	35	MPa
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**Valve Spool Type**

O	Four-way, zero opening, linear flow gain
X	Customized on demand

The position of the spool when there is no control electric signal

	Location	Pilot pressure (MPa)
0	uncertain	$\geq 1.5$
A	$P \rightarrow B, A \rightarrow T$	$\geq 1.5$
B	$P \rightarrow A, B \rightarrow T$	$\geq 1.5$

**Pilot stage control oil connection**

	Oil supply port X	Oil return port Y
4	internal control	inner row
5	External control	inner row
6	External control	out row
7	internal control	out row

**Function Code**

O	24V No enable signal input
P	15V No enable signal input
A	24V When there is no enable signal, the spool moves to the neutral position
B	24V When there is no enable signal, the spool moves to $A \rightarrow T$ or $B \rightarrow T$

**Power supply**

0	$\pm 15\text{VDC} \pm 3\%$ , pulsation $< 50\text{mVpp}$
2	24VDC (18~32VDC)

Signal corresponding to 100% rated displacement of the main spool

	input	output
A	$\pm 10\text{ V}$	$\pm 10\text{ V}$
X	$\pm 10\text{ mA}$	$\pm 10\text{ mA}, \pm 15\text{V}$ $4\sim 20\text{ mA}, \text{DC}24\text{V}$
B	$\pm 10\text{ mA}$	$\pm 10\text{ mA}$
S	$4\sim 20\text{ mA}$	$4\sim 20\text{ mA}$
M	$\pm 10\text{ V}$	$4\sim 20\text{ mA}$
E	$\pm 10\text{ V}$	$\pm 1.2\text{ V}$

**Valve socket**

S	6+PE, socket
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**Seal material**

N	Nitrile Rubber (NBR) Standard Type
V	Viton (FPM)