

SFZ141 Direct drive servo valve



■ Main Parameter

☐ Features

- Small leakage (no pilot stage flow), low power consumption (low power consumption of linear force motor), suitable for multi-valve control systems
- ➤ Low hysteresis and high resolution make the system have good control accuracy
- > Large spool driving force
- > It has a median fail-safe function.
- The position of the spool can be monitored, which is beneficial to the operation and maintenance of the system
- > With electrical zero adjustment function

General parameters		
Operating medium		Mineral oil or other fluids according to DIN 51524
Viscosity range	mm²/s	15 to 380 (30 to 45 recommended)
Oil temperature range	°C	-20 to +80 (recommended +40 to +50)
Storage temperature	°C	-20 to +80
Operating ambient temperature	°C	-40 to +70
Oil cleanliness		Maximum permissible degree of contamination of the oil, Class 6 per NAS 1638
Filtration accuracy		Recommended filter minimum filtration ratio ß5≥75
Seal material		Nitrile rubber, fluorine rubber, or other sealing ma
		terials according to user needs
Installation Requirements		Install at any position, and ensure that the pilot stage has sufficient pressure (≥2MPa) when the system starts
Weight	k g	2.75

Technical Parameters		
Work Pressure		
Oil mouth P, A, B (X port external control) MPa	≤35	
Oil mouth T (When the Y port is not used) MPa	≤5	
Oil mouth T (When using the Y port) MPa	≤21	
Rated flow (differential pressure $\Delta P = 7 M Pa$) L/min	5 10 20 40	
Zero bias %	≤±2	
Hysteresis loop %	≤0.2	
Resolution %	≤0.1	
Non-linearity %	≤10	
Asymmetry %	≤10	
Endoleak L/min	≤0.2 ≤0.4 ≤0.6 ≤1.2	



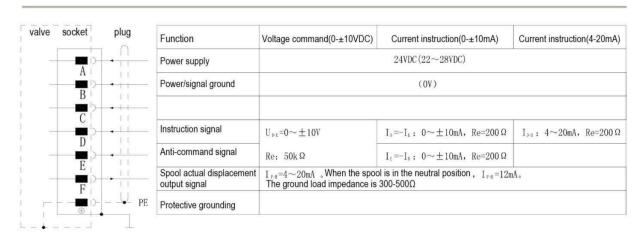
Electro-hydraulic servo valve

Amplitude bandwidth (-3dB)	Hz	≥30
Phase bandwidth(-90°)	Hz	≥40
Spool drive mode		Permanent Magnet Linear Force Motor Direct Drive
Valve body structure	,	Single stage valve, 3-way, 4-way or 2×2-way, drain port Y optional
Installation form		ISO 10372-06-05-0-92

Electrical Parameters					
Valve protection class	Conforms to standards EN60 529, IP65				
Instruction signal	0~±10V	0∼±10mA	4∼20mA		
Supply power	24VDC (22~28VDC)				
Socket	6+PE		**		
Command signal and	The stroke of the spool is proportional to	The stroke of the spool is proportional to	Spool stroke is proportional to (ID - 12mA)		
spool displacement	(UD - UE) When UD - UE=+10V, the spool	(ID= - IE), when ID=+10mA, the spool is in	When ID=+20mA, the spool is at the full open		
	is in the fully open position of $P \rightarrow A$, $B \rightarrow T$,	the fully open position of $P \rightarrow A$, $B \rightarrow T$, and	position of P→A, B→T When ID=+4mA, the		
	and the spool is in the neutral position when the spool is in the neutral position when the				
	the command signal is 0	command signal is 0	T open position		
Main spool actual	Main spool displacement output IF - B=4~20mA, when the spool is in the neutral position, IF - B=12mA, when the valve port				
displacement output	is fully open and P \rightarrow B, A \rightarrow T, IF - B=+4mA, when the valve port Fully open and P \rightarrow A, B \rightarrow T IF - B=+20mA				

Note: All signal lines must use shielded cables.

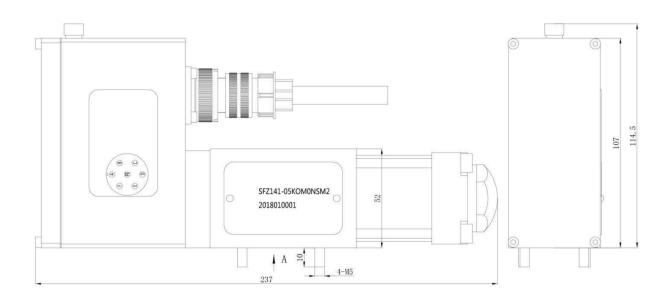
□ Electrical Wiring

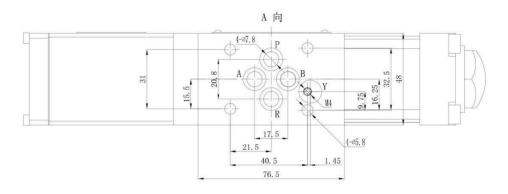


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☐ Dimensions and Interface





- The installation surface of the valve complies with ISO4401-03-03-0-94, the roughness of the installation surface of the valve is not less than $\stackrel{1.6}{\searrow}$, and the flatness is less than 0.01mm.
- In order to ensure that the servo valve can work normally, the system must be flushed before trial operation.

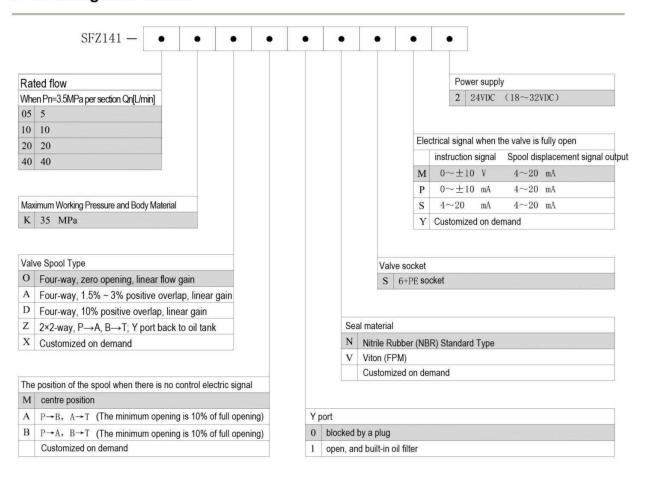
☐ Spare Parts & Accessories

Parts or accessories	Size or Specifications	Quantity
NBR O-rings		
For P, T, A and B ports	8.5×1.8	4
For Y port	8.5×1.8	1
Configuration plug (degree of protection IP65)	6+PE plug	1
Mounting screws	M5×45	4
Protective base	PP or 2A12	1



Electro-hydraulic servo valve

□ Ordering Information



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