

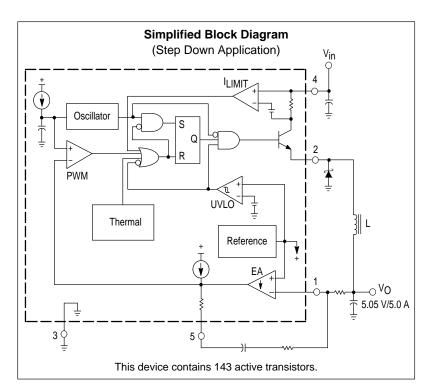
## **Power Switching Regulators**

The MC34167, MC33167 series are high performance fixed frequency power switching regulators that contain the primary functions required for dc-to-dc converters. This series was specifically designed to be incorporated in step-down and voltage-inverting configurations with a minimum number of external components and can also be used cost effectively in step-up applications.

These devices consist of an internal temperature compensated reference, fixed frequency oscillator with on-chip timing components, latching pulse width modulator for single pulse metering, high gain error amplifier, and a high current output switch.

Protective features consist of cycle–by–cycle current limiting, undervoltage lockout, and thermal shutdown. Also included is a low power standby mode that reduces power supply current to  $36~\mu A$ .

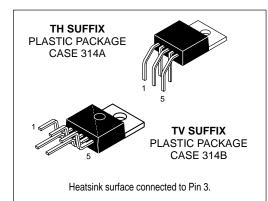
- Output Switch Current in Excess of 5.0 A
- Fixed Frequency Oscillator (72 kHz) with On-Chip Timing
- Provides 5.05 V Output without External Resistor Divider
- Precision 2% Reference
- 0% to 95% Output Duty Cycle
- Cycle-by-Cycle Current Limiting
- Undervoltage Lockout with Hysteresis
- Internal Thermal Shutdown
- Operation from 7.5 V to 40 V
- Standby Mode Reduces Power Supply Current to 36 μA
- Economical 5-Lead TO-220 Package with Two Optional Leadforms
- Also Available in Surface Mount D<sup>2</sup>PAK Package

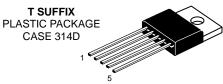


## MC34167 MC33167

# POWER SWITCHING REGULATORS

SEMICONDUCTOR TECHNICAL DATA





- Pin 1. Voltage Feedback Input
  - 2. Switch Output
  - 3. Ground
  - 4. Input Voltage/V<sub>CC</sub>
  - 5. Compensation/Standby



D2T SUFFIX LASTIC PACKAGE CASE 936A (D<sup>2</sup>PAK)

Heatsink surface (shown as terminal 6 in case outline drawing) is connected to Pin 3.

#### **ORDERING INFORMATION**

Device	Operating Temperature Range	Package
MC33167D2T		Surface Mount
MC33167T	T. 400 to 1050C	Straight Lead
MC33167TH	$T_A = -40^{\circ} \text{ to } +85^{\circ}\text{C}$	Horiz. Mount
MC33167TV		Vertical Mount
MC34167D2T		Surface Mount
MC34167T	T. 00 to 1 700C	Straight Lead
MC34167TH	$T_A = 0^{\circ} \text{ to } + 70^{\circ}\text{C}$	Horiz. Mount
MC34167TV		Vertical Mount

#### **MAXIMUM RATINGS**

Rating	Symbol	Value	Unit
Power Supply Input Voltage	Vcc	40	V
Switch Output Voltage Range	VO(switch)	–2.0 to + V <sub>in</sub>	V
Voltage Feedback and Compensation Input Voltage Range	VFB, VComp	-1.0 to + 7.0	V
Power Dissipation			
Case 314A, 314B and 314D (T <sub>A</sub> = +25°C)	PD	Internally Limited	W
Thermal Resistance, Junction-to-Ambient	θЈА	65	°C/W
Thermal Resistance, Junction-to-Case	θJC	5.0	°C/W
Case 936A (D <sup>2</sup> PAK) ( $T_A = +25^{\circ}C$ )	PD	Internally Limited	W
Thermal Resistance, Junction-to-Ambient	θJΑ	70	°C/W
Thermal Resistance, Junction-to-Case	θJC	5.0	°C/W
Operating Junction Temperature	TJ	+150	°C
Operating Ambient Temperature (Note 3)	TA		°C
MC34167 MC33167		0 to + 70 - 40 to + 85	
Storage Temperature Range	T <sub>stg</sub>	- 65 to +150	°C

**ELECTRICAL CHARACTERISTICS** ( $V_{CC} = 12 \text{ V}$ , for typical values  $T_A = +25^{\circ}\text{C}$ , for min/max values  $T_A$  is the operating ambient temperature range that applies [Notes 2, 3], unless otherwise noted.)

aracteristic		Symbol	Min	<b>T</b>	l	
	Characteristic			Тур	Max	Unit
10 V)	$T_A = +25^{\circ}C$ $T_A = T_{low}$ to $T_{high}$	fosc	65 62	72 -	79 81	kHz
eshold	$T_A = + 25^{\circ}C$ $T_A = T_{low}$ to $T_{high}$	V <sub>FB(th)</sub>	4.95 4.85	5.05 -	5.15 5.20	V
V to 40 V, T <sub>A</sub> =	+25°C)	Regline	_	0.03	0.078	%/V
FB(th) + 0.15 V	)	I <sub>IB</sub>	-	0.15	1.0	μΑ
o (V <sub>CC</sub> = 10 V	to 20 V, f = 120 Hz)	PSRR	60	80	-	dB
Output Voltage Swing High State ( $I_{Source} = 75 \mu\text{A},  V_{FB} = 4.5 \text{V}$ ) Low State ( $I_{Sink} = 0.4 \text{mA},  V_{FB} = 5.5 \text{V}$ )			4.2 -	4.9 1.6	- 1.9	V
				•		
	` ,	DC <sub>(max)</sub> DC <sub>(min)</sub>	92 0	95 0	100 0	%
	·					
ration ( $V_{CC} = 7$	7.5 V, I <sub>Source</sub> = 5.0 A)	V <sub>sat</sub>	_	(V <sub>CC</sub> -1.5)	(V <sub>CC</sub> -1.8)	V
40 V, Pin 2 = G	nd)	I <sub>sw(off)</sub>	-	0	100	μА
c = 7.5 V)		Ipk(switch)	5.5	6.5	8.0	Α
Switching Times ( $V_{CC}$ = 40 V, $I_{pk}$ = 5.0 A, L = 225 $\mu$ H, $T_A$ = +25°C) Output Voltage Rise Time Output Voltage Fall Time			_ _	100 50	200 100	ns
Г						
reasing, T <sub>A</sub> = +	25°C)	V <sub>th</sub> (UVLO)	5.5	5.9	6.3	V
Hysteresis (V <sub>CC</sub> Decreasing, T <sub>A</sub> = +25°C)			0.6	0.9	1.2	V
Power Supply Current ( $T_A = +25^{\circ}C$ ) Standby ( $V_{CC} = 12 \text{ V}$ , $V_{Comp} < 0.15 \text{ V}$ ) Operating ( $V_{CC} = 40 \text{ V}$ , Pin 1 = Gnd for maximum duty cycle)			<u> </u>	36 40	100 60	μA mA
	PB(th) + 0.15 V o (VCC = 10 V h State (ISource v State (ISink = 10 V) Maxin Minin Pation (VCC = 7 V) 40 V, Pin 2 = Gi C = 7.5 V) Ipk = 5.0 A, L = 10 V reasing, TA = +25°C) +25°C) comp < 0.15 V)	TA = $T_{low}$ to $T_{high}$ Peshold  TA =+ 25°C  TA = $T_{low}$ to $T_{high}$ To to 40 V, $T_A$ = +25°C)  FB(th) + 0.15 V)  To (VCC = 10 V to 20 V, f = 120 Hz)  The State ( $I_{Source}$ = 75 $\mu$ A, $V_{FB}$ = 4.5 V)  The State ( $I_{Sink}$ = 0.4 mA, $V_{FB}$ = 5.5 V)  Maximum ( $V_{FB}$ = 0 V)  Minimum ( $V_{Comp}$ = 1.9 V)  The State ( $I_{Sink}$ = 0.4 mA, $I_{FB}$ = 5.0 A)  The State ( $I_{Sink}$ = 0.4 mA, $I_{FB}$ = 5.5 V)  The State ( $I_{Sink}$ = 0.4 mA, $I_{FB}$ = 5.5 V)  The State ( $I_{Sink}$ = 0.4 mA, $I_{FB}$ = 4.5 V)  The State ( $I_{Sink}$ = 0.4 mA, $I_{FB}$ = 5.5 V)  The State ( $I_{Sink}$ = 0.4 mA, $I_{FB}$ = 5.5 V)  The State ( $I_{Sink}$ = 0.4 mA, $I_{FB}$ = 4.5 V)  The State ( $I_{Sink}$ = 0.4 mA, $I_{FB}$ = 0.5 V)  The State ( $I_{Sink}$ = 0.4 mA, $I_{F$	$T_{A} = T_{low} \text{ to } T_{high}$ $T_{A} = T_{low} \text{ to } T_{high}$ $V \text{ to } 40 \text{ V}, T_{A} = +25^{\circ}\text{C}$ $T_{A} = T_{low} \text{ to } T_{high}$ $V \text{ to } 40 \text{ V}, T_{A} = +25^{\circ}\text{C})$ $F_{B}(th) + 0.15 \text{ V})$ $V_{B}(th) + 0.15 \text{ V}$ $V_{C}(th) + $	$T_{A} = T_{low} \text{ to } T_{high}$ $T_{A} = T_{lo$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$

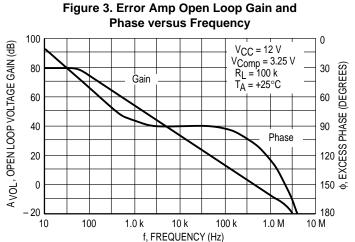
NOTES: 1. Maximum package power dissipation limits must be observed to prevent thermal shutdown activation.

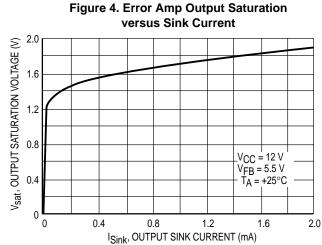
2. Low duty cycle pulse techniques are used during test to maintain junction temperature as close to ambient as possible.

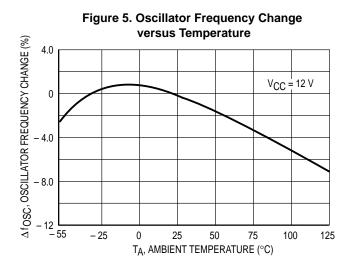
3. T<sub>low</sub> = 0°C for MC34167 T<sub>high</sub> = +70°C for MC34167 = +85°C for MC33167

Figure 1. Voltage Feedback Input Threshold VFB(th), VOLTAGE FEEDBACK INPUT THRESHOLD (V) versus Temperature 5.25 V<sub>CC</sub> = 12 V -VFB(th) Max = 5.15 V 5.17 5.09  $V_{FB(th)}$  Typ = 5.05 V 5.01 VFB(th) Min = 4.95 V 4.93 4.85 L - 55 - 25 0 25 50 75 100 125 TA, AMBIENT TEMPERATURE (°C)

Figure 2. Voltage Feedback Input Bias **Current versus Temperature** 100 V<sub>CC</sub> = 12 V V<sub>FB</sub> = V<sub>FB(th)</sub> IB, INPUT BIAS CURRENT (nA) 80 60 40 20 0 <del>-</del> 55 - 25 0 25 50 75 100 125 TA, AMBIENT TEMPERATURE (°C)







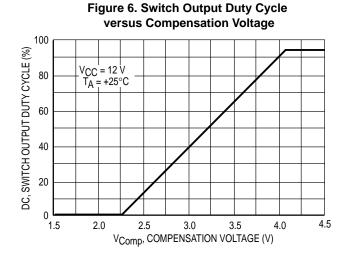
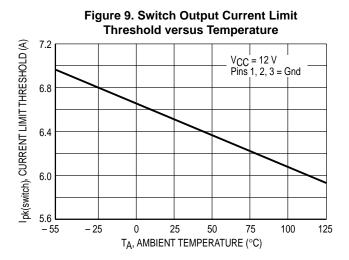
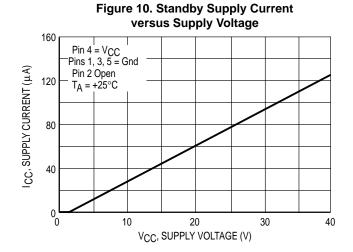
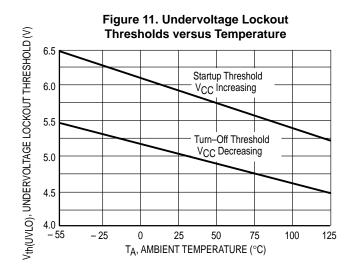


Figure 7. Switch Output Source Saturation versus Source Current  $V_{CC}$   $T_{A} = +25^{\circ}C$   $T_{A} = +25^{\circ}C$ 

Figure 8. Negative Switch Output Voltage versus Temperature 0 Gnd V<sub>Sw</sub>, SWITCH OUTPUT VOLTAGE (V) - 0.2 V<sub>CC</sub> = 12 V Pin 5 = 2.0 V Pins 1, 3 = GndPin 2 Driven Negative  $I_{SW} = 100 \mu A$ - 0.6 - 0.8  $I_{SW} = 10 \text{ mA}$ -1.0 -1.2 L - 55 - 25 25 50 75 100 125 TA, AMBIENT TEMPERATURE (°C)







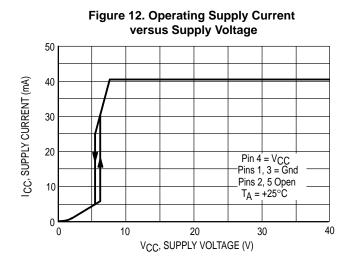


Figure 13. MC34167 Representative Block Diagram

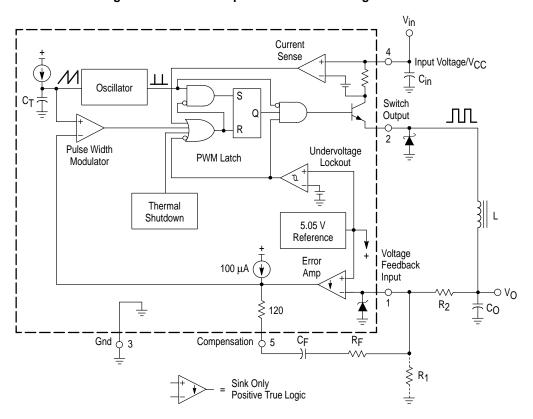
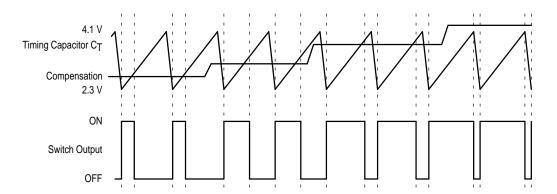


Figure 14. Timing Diagram



# MC34167 MC33167 INTRODUCTION

The MC34167, MC33167 series are monolithic power switching regulators that are optimized for dc-to-dc converter applications. These devices operate as fixed frequency, voltage mode regulators containing all the active functions required to directly implement step-down and voltage-inverting converters with a minimum number of external components. They can also be used cost effectively in step-up converter applications. Potential markets include automotive, computer, industrial, and cost sensitive consumer products. A description of each section of the device is given below with the representative block diagram shown in Figure 13.

#### Oscillator

The oscillator frequency is internally programmed to 72 kHz by capacitor  $C_T$  and a trimmed current source. The charge to discharge ratio is controlled to yield a 95% maximum duty cycle at the Switch Output. During the discharge of  $C_T$ , the oscillator generates an internal blanking pulse that holds the inverting input of the AND gate high, disabling the output switch transistor. The nominal oscillator peak and valley thresholds are 4.1 V and 2.3 V respectively.

#### **Pulse Width Modulator**

The Pulse Width Modulator consists of a comparator with the oscillator ramp voltage applied to the noninverting input, while the error amplifier output is applied into the inverting input. Output switch conduction is initiated when C<sub>T</sub> is discharged to the oscillator valley voltage. As C<sub>T</sub> charges to a voltage that exceeds the error amplifier output, the latch resets, terminating output transistor conduction for the duration of the oscillator ramp—up period. This PWM/Latch combination prevents multiple output pulses during a given oscillator clock cycle. Figures 6 and 14 illustrate the switch output duty cycle versus the compensation voltage.

#### **Current Sense**

The MC34167 series utilizes cycle—by—cycle current limiting as a means of protecting the output switch transistor from overstress. Each on cycle is treated as a separate situation. Current limiting is implemented by monitoring the output switch transistor current buildup during conduction, and upon sensing an overcurrent condition, immediately turning off the switch for the duration of the oscillator ramp—up period.

The collector current is converted to a voltage by an internal trimmed resistor and compared against a reference by the Current Sense comparator. When the current limit threshold is reached, the comparator resets the PWM latch. The current limit threshold is typically set at 6.5 A. Figure 9 illustrates switch output current limit threshold versus temperature.

#### **Error Amplifier and Reference**

A high gain Error Amplifier is provided with access to the inverting input and output. This amplifier features a typical dc voltage gain of 80 dB, and a unity gain bandwidth of 600 kHz with 70 degrees of phase margin (Figure 3). The noninverting input is biased to the internal 5.05 V reference and is not pinned out. The reference has an accuracy of  $\pm$  2.0% at room temperature. To provide 5.0 V at the load, the reference is programmed 50 mV above 5.0 V to compensate for a 1.0% voltage drop in the cable and connector from the

converter output. If the converter design requires an output voltage greater than 5.05 V, resistor  $R_1$  must be added to form a divider network at the feedback input as shown in Figures 13 and 18. The equation for determining the output voltage with the divider network is:

$$V_{out} = 5.05 \left( \frac{R_2}{R_1} + 1 \right)$$

External loop compensation is required for converter stability. A simple low-pass filter is formed by connecting a resistor (R2) from the regulated output to the inverting input, and a series resistor-capacitor (RF, CF) between Pins 1 and 5. The compensation network component values shown in each of the applications circuits were selected to provide stability over the tested operating conditions. The step-down converter (Figure 18) is the easiest to compensate for stability. The step-up (Figure 20) and voltage-inverting (Figure 22) configurations operate as continuous conduction flyback converters, and are more difficult to compensate. The simplest way to optimize the compensation network is to observe the response of the output voltage to a step load change, while adjusting RF and CF for critical damping. The final circuit should be verified for stability under four boundary conditions. These conditions are minimum and maximum input voltages, with minimum and maximum loads.

By clamping the voltage on the error amplifier output (Pin 5) to less than 150 mV, the internal circuitry will be placed into a low power standby mode, reducing the power supply current to  $36~\mu\text{A}$  with a 12 V supply voltage. Figure 10 illustrates the standby supply current versus supply voltage.

The Error Amplifier output has a 100  $\mu$ A current source pull—up that can be used to implement soft—start. Figure 17 shows the current source charging capacitor CSS through a series diode. The diode disconnects CSS from the feedback loop when the 1.0 M resistor charges it above the operating range of Pin 5.

#### **Switch Output**

The output transistor is designed to switch a maximum of 40 V, with a minimum peak collector current of 5.5 A. When configured for step–down or voltage–inverting applications, as in Figures 18 and 22, the inductor will forward bias the output rectifier when the switch turns off. Rectifiers with a high forward voltage drop or long turn on delay time should not be used. If the emitter is allowed to go sufficiently negative, collector current will flow, causing additional device heating and reduced conversion efficiency. Figure 8 shows that by clamping the emitter to 0.5 V, the collector current will be in the range of 100  $\mu\text{A}$  over temperature. A 1N5825 or equivalent Schottky barrier rectifier is recommended to fulfill these requirements.

#### **Undervoltage Lockout**

An Undervoltage Lockout comparator has been incorporated to guarantee that the integrated circuit is fully functional before the output stage is enabled. The internal reference voltage is monitored by the comparator which enables the output stage when  $V_{CC}$  exceeds 5.9 V. To prevent erratic output switching as the threshold is crossed, 0.9 V of hysteresis is provided.

#### **Thermal Protection**

Internal Thermal Shutdown circuitry is provided to protect the integrated circuit in the event that the maximum junction temperature is exceeded. When activated, typically at 170°C, the latch is forced into a 'reset' state, disabling the output switch. This feature is provided to prevent catastrophic failures

from accidental device overheating. It is not intended to be used as a substitute for proper heatsinking. The MC34167 is contained in a 5–lead TO–220 type package. The tab of the package is common with the center pin (Pin 3) and is normally connected to ground.

#### **DESIGN CONSIDERATIONS**

Do not attempt to construct a converter on wire—wrap or plug—in prototype boards. Special care should be taken to separate ground paths from signal currents and ground paths from load currents. All high current loops should be kept as short as possible using heavy copper runs to minimize ringing and radiated EMI. For best operation, a tight

component layout is recommended. Capacitors  $C_{in}$ ,  $C_{O}$ , and all feedback components should be placed as close to the IC as physically possible. It is also imperative that the Schottky diode connected to the Switch Output be located as close to the IC as possible.

Figure 15. Low Power Standby Circuit

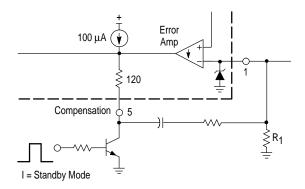


Figure 16. Over Voltage Shutdown Circuit

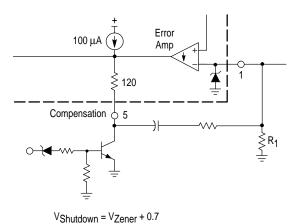


Figure 17. Soft-Start Circuit

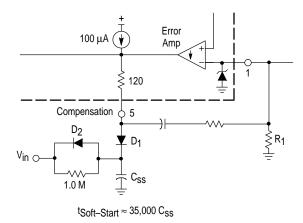
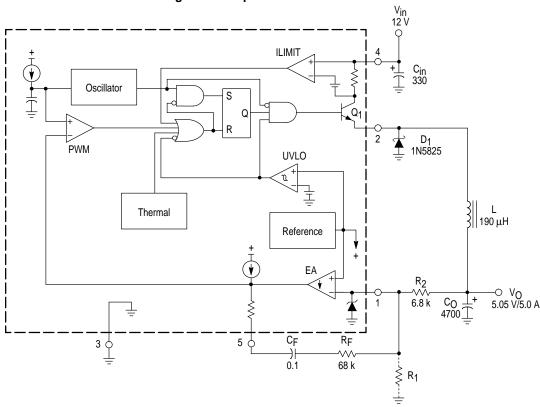


Figure 18. Step-Down Converter

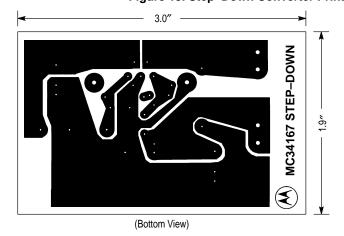


Test	Conditions	Results
Line Regulation	$V_{in} = 10 \text{ V to } 36 \text{ V}, I_{O} = 5.0 \text{ A}$	4.0 mV = ± 0.039%
Load Regulation	V <sub>in</sub> = 12 V, I <sub>O</sub> = 0.25 A to 5.0 A	1.0 mV = ± 0.01%
Output Ripple	V <sub>in</sub> = 12 V, I <sub>O</sub> = 5.0 A	20 mV <sub>pp</sub>
Short Circuit Current	$V_{in} = 12 \text{ V}, R_L = 0.1 \Omega$	6.5 A
Efficiency	V <sub>in</sub> = 12 V, I <sub>O</sub> = 5.0 A V <sub>in</sub> = 24 V, I <sub>O</sub> = 5.0 A	78.9% 82.6%

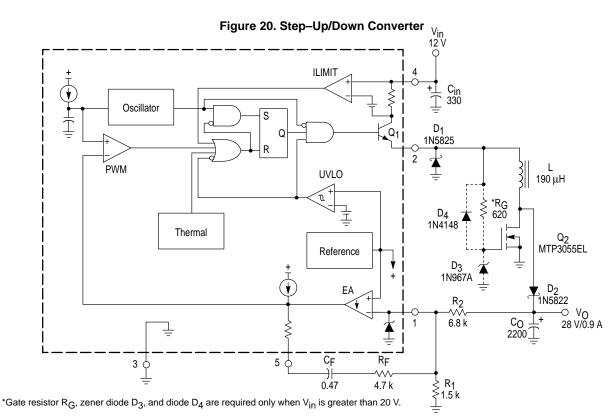
 $L=\mbox{Coilcraft M1496-A or General Magnetics Technology GMT-0223, 42 turns of \#16 AWG on Magnetics Inc. 58350-A2 core. Heatsink = AAVID Engineering Inc. 5903B, or 5930B.}$ 

The Step–Down Converter application is shown in Figure 18. The output switch transistor  $Q_1$  interrupts the input voltage, generating a squarewave at the  $LC_0$  filter input. The filter averages the squarewaves, producing a dc output voltage that can be set to any level between  $V_{in}$  and  $V_{ref}$  by controlling the percent conduction time of  $Q_1$  to that of the total oscillator cycle time. If the converter design requires an output voltage greater than 5.05 V, resistor  $R_1$  must be added to form a divider network at the feedback input.

Figure 19. Step-Down Converter Printed Circuit Board and Component Layout



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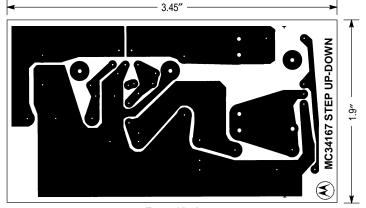
Test	Conditions	Results
Line Regulation	V <sub>in</sub> = 10 V to 24 V, I <sub>O</sub> = 0.9 A	10 mV = ± 0.017%
Load Regulation	V <sub>in</sub> = 12 V, I <sub>O</sub> = 0.1 A to 0.9 A	30 mV = ± 0.053%
Output Ripple	V <sub>in</sub> = 12 V, I <sub>O</sub> = 0.9 A	140 mV <sub>pp</sub>
Short Circuit Current	$V_{in} = 12 \text{ V}, R_L = 0.1 \Omega$	6.0 A
Efficiency	V <sub>in</sub> = 12 V, I <sub>O</sub> = 0.9 A V <sub>in</sub> = 24 V, I <sub>O</sub> = 0.9 A	80.1% 87.8%

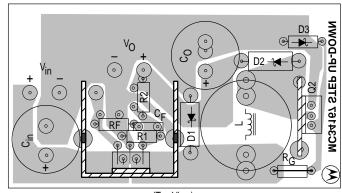
L = Coilcraft M1496–A or General Magnetics Technology GMT–0223, 42 turns of #16 AWG on Magnetics Inc. 58350–A2 core.

Heatsink = AAVID Engineering Inc. MC34167: 5903B, or 5930B MTP3055EL: 5925B

Figure 20 shows that the MC34167 can be configured as a step–up/down converter with the addition of an external power MOSFET. Energy is stored in the inductor during the ON time of transistors  $Q_1$  and  $Q_2$ . During the OFF time, the energy is transferred, with respect to ground, to the output filter capacitor and load. This circuit configuration has two significant advantages over the basic step–up converter circuit. The first advantage is that output short circuit protection is provided by the MC34167, since  $Q_1$  is directly in series with  $V_{In}$  and the load. Second, the output voltage can be programmed to be less than  $V_{In}$ . Notice that during the OFF time, the inductor forward biases diodes  $D_1$  and  $D_2$ , transferring its energy with respect to ground rather than with respect to  $V_{In}$ . When operating with  $V_{In}$  greater than 20 V, a gate protection network is required for the MOSFET. The network consists of components  $R_G$ ,  $D_3$ , and  $D_4$ .

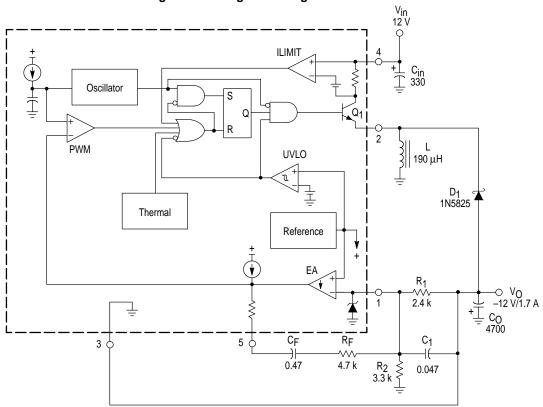
Figure 21. Step-Up/Down Converter Printed Circuit Board and Component Layout





(Bottom View) (Top View)

Figure 22. Voltage-Inverting Converter

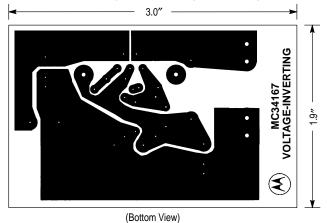


Test	Conditions	Results
Line Regulation	V <sub>in</sub> = 10 V to 24 V, I <sub>O</sub> = 1.7 A	15 mV = ± 0.61%
Load Regulation	$V_{in} = 12 \text{ V}, I_{O} = 0.1 \text{ A to } 1.7 \text{ A}$	4.0 mV = ± 0.020%
Output Ripple	V <sub>in</sub> = 12 V, I <sub>O</sub> = 1.7 A	78 mV <sub>pp</sub>
Short Circuit Current	$V_{in} = 12 \text{ V}, R_L = 0.1 \Omega$	5.7 A
Efficiency	V <sub>in</sub> = 12 V, I <sub>O</sub> = 1.7 A V <sub>in</sub> = 24 V, I <sub>O</sub> = 1.7 A	79.5% 86.2%

L = Coilcraft M1496–A or General Magnetics Technology GMT–0223, 42 turns of #16 AWG on Magnetics Inc. 58350–A2 core. Heatsink = AAVID Engineering Inc. 5903B, or 5930B.

Two potential problems arise when designing the standard voltage—inverting converter with the MC34167. First, the Switch Output emitter is limited to -1.5 V with respect to the ground pin and second, the Error Amplifier's noninverting input is internally committed to the reference and is not pinned out. Both of these problems are resolved by connecting the IC ground pin to the converter's negative output as shown in Figure 22. This keeps the emitter of  $Q_1$  positive with respect to the ground pin and has the effect of reversing the Error Amplifier inputs. Note that the voltage drop across  $R_1$  is equal to 5.05 V when the output is in regulation.

Figure 23. Voltage-Inverting Converter Printed Circuit Board and Component Layout



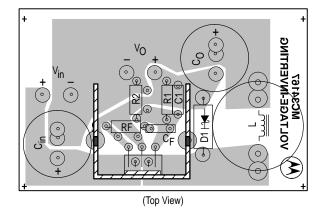
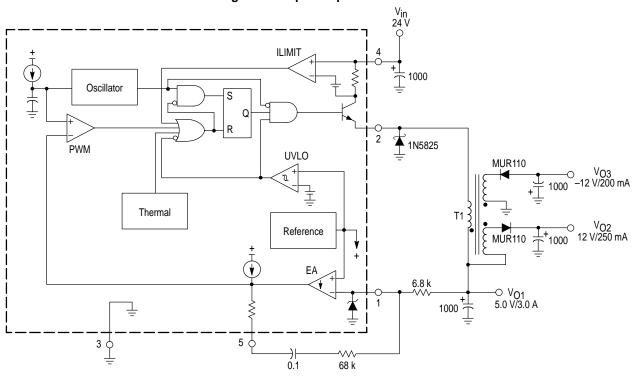


Figure 24. Triple Output Converter



Tests		Conditions	Results
Line Regulation	5.0 V 12 V –12 V	$V_{in}$ = 15 V to 30 V, $I_{O1}$ = 3.0 A, $I_{O2}$ = 250 mA, $I_{O3}$ = 200 mA	$3.0 \text{ mV} = \pm 0.029\%$ $572 \text{ mV} = \pm 2.4\%$ $711 \text{ mV} = \pm 2.9\%$
Load Regulation	5.0 V 12 V –12 V	$\begin{aligned} &\text{V}_{\text{in}} = 24 \text{ V, I}_{\text{O1}} = 30 \text{ mA to } 3.0 \text{ A, I}_{\text{O2}} = 250 \text{ mA, I}_{\text{O3}} = 200 \text{ mA} \\ &\text{V}_{\text{in}} = 24 \text{ V, I}_{\text{O1}} = 3.0 \text{ A, I}_{\text{O2}} = 100 \text{ mA to } 250 \text{ mA, I}_{\text{O3}} = 200 \text{ mA} \\ &\text{V}_{\text{in}} = 24 \text{ V, I}_{\text{O1}} = 3.0 \text{ A, I}_{\text{O2}} = 250 \text{ mA, I}_{\text{O3}} = 75 \text{ mA to } 200 \text{ mA} \end{aligned}$	1.0 mV = $\pm$ 0.009% 409 mV = $\pm$ 1.5% 528 mV = $\pm$ 2.0%
Output Ripple	5.0 V 12 V –12 V	$V_{in} = 24 \text{ V}, I_{O1} = 3.0 \text{ A}, I_{O2} = 250 \text{ mA}, I_{O3} = 200 \text{ mA}$	75 mV <sub>pp</sub> 20 mV <sub>pp</sub> 20 mV <sub>pp</sub>
Short Circuit Current	5.0 V 12 V –12 V	$V_{in}$ = 24 V, $R_L$ = 0.1 $\Omega$	6.5 A 2.7 A 2.2 A
Efficiency	TOTAL	V <sub>in</sub> = 24 V, I <sub>O1</sub> = 3.0 A, I <sub>O2</sub> = 250 mA, I <sub>O3</sub> = 200 mA	84.2%

T1 = Primary: Coilcraft M1496-A or General Magnetics Technology GMT-0223, 42 turns of #16 AWG on Magnetics Inc. 58350-A2 core.

Secondary: VO2 - 69 turns of #26 AWG

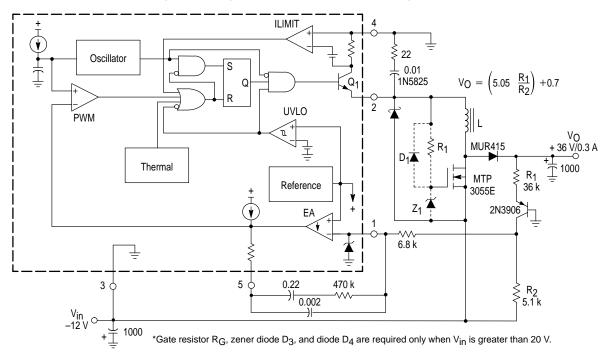
 $V_{O3}$  – 104 turns of #28 AWG Heatsink = AAVID Engineering Inc. 5903B, or 5930B.

Multiple auxiliary outputs can easily be derived by winding secondaries on the main output inductor to form a transformer. The secondaries must be connected so that the energy is delivered to the auxiliary outputs when the Switch Output turns off. During the OFF time, the voltage across the primary winding is regulated by the feedback loop, yielding a constant Volts/Turn ratio. The number of turns for any given secondary voltage can be calculated by the following equation:

$$\text{\# TURNS}_{\text{(SEC)}} = \frac{\text{VO(SEC)} + \text{VF(SEC)}}{\left(\frac{\text{VO(PRI)} + \text{VF(PRI)}}{\text{\#TURNS(PRI)}}\right)}$$

Note that the 12 V winding is stacked on top of the 5.0 V output. This reduces the number of secondary turns and improves lead regulation. For best auxiliary regulation, the auxiliary outputs should be less than 33% of the total output power.

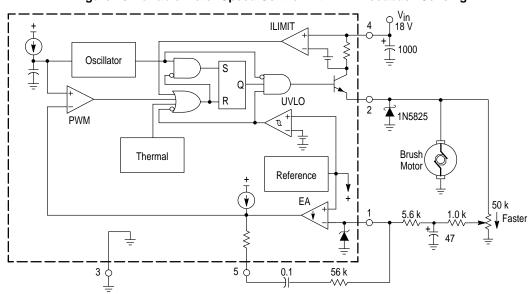
Figure 25. Negative Input/Positive Output Regulator



Test	Conditions	Results
Line Regulation	$V_{in} = -10 \text{ V to} - 20 \text{ V}, I_{O} = 0.3 \text{ A}$	266 mV = ± 0.38%
Load Regulation	$V_{in} = -12 \text{ V}, I_O = 0.03 \text{ A to } 0.3 \text{ A}$	7.90 mV = ±1.1%
Output Ripple	$V_{in} = -12 \text{ V}, I_{O} = 0.3 \text{ A}$	100 mV <sub>pp</sub>
Efficiency	$V_{in} = -12 \text{ V}, I_O = 0.3 \text{ A}$	78.4%

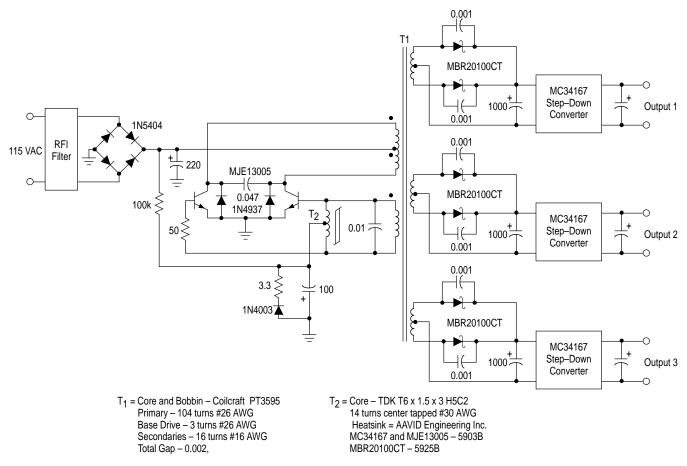
 $L=General\ Magnetics\ Technology\ GMT-0223,\ 42\ turns\ of\ \#16\ AWG\ on\ Magnetics\ Inc.\ 58350-A2\ core.\ Heatsink=\ AAVID\ Engineering\ Inc.\ 5903B\ or\ 5930B$ 

Figure 26. Variable Motor Speed Control with EMF Feedback Sensing



Test	Conditions	Results
Low Speed Line Regulation	V <sub>in</sub> = 12 V to 24 V	1760 RPM ±1%
High Speed Line Regulation	V <sub>in</sub> = 12 V to 24 V	3260 RPM ± 6%

Figure 27. Off-Line Preconverter



The MC34167 can be used cost effectively in off–line applications even though it is limited to a maximum input voltage of 40 V. Figure 27 shows a simple and efficient method for converting the AC line voltage down to 24 V. This preconverter has a total power rating of 125 W with a conversion efficiency of 90%. Transformer T<sub>1</sub> provides output isolation from the AC line and isolation between each of the secondaries. The circuit self–oscillates at 50 kHz and is controlled by the saturation characteristics of T<sub>2</sub>. Multiple MC34167 post regulators can be used to provide accurate independently regulated outputs for a distributed power system.

80 3.5 MAXIMUM POWER DISSIPATION (W)  $P_{D(max)}$  for  $T_A = +50^{\circ}C$  $R_{\Theta JA}$ , THERMAL RESISTANCE 3.0 JUNCTION-TO-AIR (°C/W) Free Air Mounted Vertically 2.0 oz. Copper 60 Minimum 50 2.0 Size Pad 40  $R_{\theta JA}$ ځ 1.0 30 5.0 30 0 15 25

L, LENGTH OF COPPER (mm)

Figure 28. D<sup>2</sup>PAK Thermal Resistance and Maximum Power Dissipation versus P.C.B. Copper Length

**Table 1. Design Equations** 

10.01	Table 1. Design Equations				
Calculation	Step-Down	Step-Up/Down	Voltage-Inverting		
ton toff (Notes 1, 2)	Vout + VF Vin - Vsat - Vout	$\frac{V_{Out} + VF1 + VF2}{Vin - V_{SatQ1} - V_{SatQ2}}$	<u> V<sub>out</sub>  + V</u> F V <sub>in</sub> − V <sub>sat</sub>		
<sup>t</sup> on	$\frac{\frac{ton}{toff}}{fosc\!\left(\!\frac{ton}{toff} + 1\right)}$	$\frac{\frac{t_{on}}{t_{off}}}{f_{osc}\left(\frac{t_{on}}{t_{off}}+1\right)}$	$\frac{\frac{t_{On}}{t_{Off}}}{f_{OSC}\left(\frac{t_{On}}{t_{Off}}+1\right)}$		
Duty Cycle (Note 3)	ton fosc	<sup>t</sup> on <sup>f</sup> osc	t <sub>on</sub> f <sub>osc</sub>		
I <sub>L avg</sub>	l <sub>out</sub>	$I_{Out}\left(\frac{t_{On}}{t_{Off}} + 1\right)$	$I_{out}\left(\frac{t_{on}}{t_{off}} + 1\right)$		
lpk(switch)	$I_L \text{ avg } + \frac{\Delta I_L}{2}$	$I_{L avg} + \frac{\Delta I_{L}}{2}$	$I_{L avg} + \frac{\Delta I_{L}}{2}$		
L	$\left(\frac{V_{in} - V_{sat} - V_{out}}{\Delta I_L}\right) t_{on}$	$\left(\frac{V_{\text{in}} - V_{\text{satQ1}} - V_{\text{satQ2}}}{\Delta I_{\text{L}}}\right)$ ton	$\left(\frac{V_{in} - V_{sat}}{\Delta I_L}\right) t_{on}$		
Vripple(pp)	$\Delta I_L \sqrt{\left(\frac{1}{8f_{OSC}C_O}\right)^2 + (ESR)^2}$	$\left(\frac{t_{on}}{t_{off}} + 1\right)\sqrt{\left(\frac{1}{t_{osc}C_{o}}\right)^{2} + (ESR)^{2}}$	$\left(\frac{t_{on}}{t_{off}} + 1\right)\sqrt{\left(\frac{1}{t_{osc}C_{o}}\right)^{2} + (ESR)^{2}}$		
V <sub>out</sub>	$V_{ref}\left(\frac{R_2}{R_1} + 1\right)$	$V_{ref}\left(\frac{R_2}{R_1} + 1\right)$	$V_{ref}\left(\frac{R_2}{R_1} + 1\right)$		

The following converter characteristics must be chosen:

Vout - Desired output voltage.

lout – Desired output current.
ΔI<sub>L</sub> – Desired peak–to–peak inductor ripple current. For maximum output current especially when the duty cycle is greater than 0.5, it is suggested that  $\Delta I_L$  be chosen minimum current limit threshold of 5.5 A. If the design goal is to use a minimum inductance value, let  $\Delta I_L$  = 2 ( $I_L$  avg). This will proportionally reduce the converter's output current capability.

Vripple(pp) - Desired peak-to-peak output ripple voltage. For best performance, the ripple voltage should be kept to less than 2% of Vout. Capacitor CO should be a low equivalent series resistance (ESR) electrolytic designed for switching regulator applications.

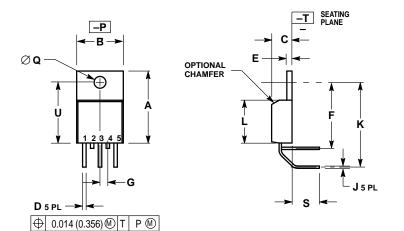
NOTES: 1. V<sub>sat</sub> – Switch Output source saturation voltage, refer to Figure 7.

2. V<sub>F</sub> – Output rectifier forward voltage drop. Typical value for 1N5822 Schottky barrier rectifier is 0.35 V.

3. Duty cycle is calculated at the minimum operating input voltage and must not exceed the guaranteed minimum DC<sub>(max)</sub> specification of 0.92.

## MC34167 MC33167 **OUTLINE DIMENSIONS**

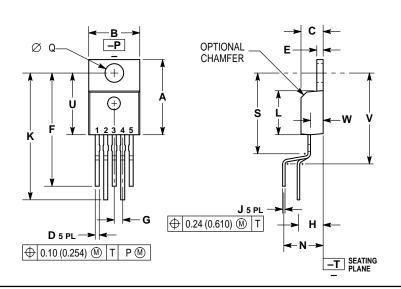
#### **TH SUFFIX** PLASTIC PACKAGE CASE 314A-03



- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION D DOES NOT INCLUDE INTERCONNECT BAR (DAMBAR) PROTRUSION. DIMENSION D INCLUDING PROTRUSION SHALL NOT EXCEED 0.043 (1.092) MAXIMUM.

	INCHES		MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.572	0.613	14.529	15.570
В	0.390	0.415	9.906	10.541
С	0.170	0.180	4.318	4.572
D	0.025	0.038	0.635	0.965
Е	0.048	0.055	1.219	1.397
F	0.570	0.585	14.478	14.859
G	0.067	BSC	1.702	BSC
J	0.015	0.025	0.381	0.635
K	0.730	0.745	18.542	18.923
L	0.320	0.365	8.128	9.271
Q	0.140	0.153	3.556	3.886
S	0.210	0.260	5.334	6.604
U	0.468	0.505	11 888	12 827

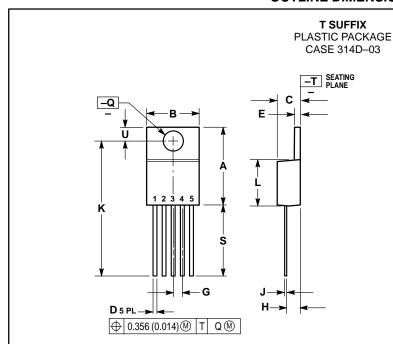
#### **TV SUFFIX** PLASTIC PACKAGE CASE 314B-05



- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION D DOES NOT INCLUDE INTERCONNECT BAR (DAMBAR) PROTRUSION. DIMENSION D INCLUDING PROTRUSION SHALL NOT EXCEED 0.043 (1.092) MAXIMUM.

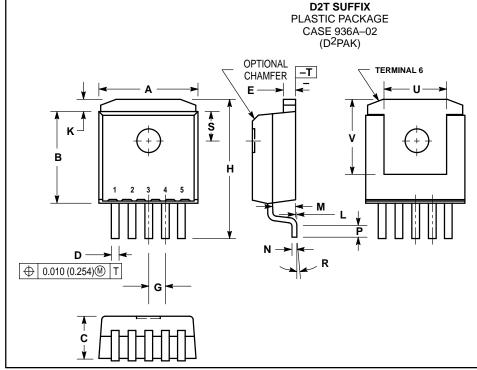
	INCHES		MILLIN	IETERS
DIM	MIN	MAX	MIN	MAX
Α	0.572	0.613	14.529	15.570
В	0.390	0.415	9.906	10.541
С	0.170	0.180	4.318	4.572
D	0.025	0.038	0.635	0.965
E	0.048	0.055	1.219	1.397
F	0.850	0.935	21.590	23.749
G	0.06	7 BSC	1.70	02 BSC
Н	0.16	66 BSC	4.2	16 BSC
J	0.015	0.025	0.381	0.635
K	0.900	1.100	22.860	27.940
L	0.320	0.365	8.128	9.271
N	0.320 BSC		8.12	28 BSC
Q	0.140	0.153	3.556	3.886
S	-	0.620	_	15.748
U	0.468	0.505	11.888	12.827
٧	-	0.735	_	18.669
W	0.090	0.110	2.286	2.794

### MC34167 MC33167 **OUTLINE DIMENSIONS**



- NOT EXCEED 10.92 (0.043) MAXIMUM.

	INC	HES	MILLIMETERS	
DIM	MIN	MAX	MIN	MAX
Α	0.572	0.613	14.529	15.570
В	0.390	0.415	9.906	10.541
С	0.170	0.180	4.318	4.572
D	0.025	0.038	0.635	0.965
E	0.048	0.055	1.219	1.397
G	0.067 BSC		1.702 BSC	
Н	0.087	0.112	2.210	2.845
J	0.015	0.025	0.381	0.635
K	1.020	1.065	25.908	27.051
L	0.320	0.365	8.128	9.271
Q	0.140	0.153	3.556	3.886
U	0.105	0.117	2.667	2.972
S	0.543	0.582	13.792	14.783



#### NOTES:

- IOTES:

  1 DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

  2 CONTROLLING DIMENSION: INCH.

  3 TAB CONTOUR OPTIONAL WITHIN DIMENSIONS A AND K.

  4 DIMENSIONS U AND V ESTABLISH A MINIMUM MOUNTING SURFACE FOR TERMINAL 6.

  5 DIMENSIONS A AND B DO NOT INCLUDE MOLD FLASH OR GATE PROTRUSIONS. MOLD FLASH AND GATE PROTRUSIONS. MOLD FLASH AND GATE PROTRUSIONS NOT TO EXCEED 0.025 (0.635) MAXIMUM.

	INCHES		MILLIMETERS	
DIM	MIN	MAX	MIN	MAX
Α	0.386	0.403	9.804	10.236
В	0.356	0.368	9.042	9.347
С	0.170	0.180	4.318	4.572
D	0.026	0.036	0.660	0.914
E	0.045	0.055	1.143	1.397
G	0.067 BSC		1.702 BSC	
Н	0.539	0.579	13.691	14.707
K	0.050 REF		1.270 REF	
L	0.000	0.010	0.000	0.254
M	0.088	0.102	2.235	2.591
N	0.018	0.026	0.457	0.660
Р	0.058	0.078	1.473	1.981
R	5°REF		5° REF	
S	0.116 REF		2.946 REF	
U	0.200 MIN		5.080 MIN	
٧	0.250 MIN		6.350 MIN	

