



ET-M8196F

Ethernet Remote Unit with High-speed, DSP-based, 6-axis Motion Control Module

₱ Features

- Remote control via Modbus TCP
- DSP-based motion control module
- Pulse output rate: 4 MHz (Max.)
- Maximum encoder input frequency: 12 MHz
- Independent 6-axis motion control
- 2- to 6-axis linear/ 2- to 3-axis circular/ helical interpolation function
- Continuous interpolation
- 4-step home mode with auto-searching
- Synchronized start motion
- Programmable T/S-curve acceleration and deceleration
- Software limit protection
- Software FIFO for arbitrary curve motion
- High-speed position latch
- High-speed compare trigger and auto-increment compare
- Expandable remote I/O: 128 DI and 128 DO via a two-wire FRnet interface.



■ Introduction

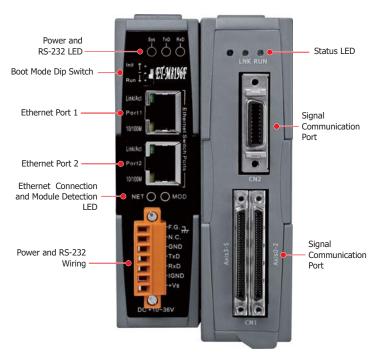
The **ET-M8196F** is a compact remote motion control device which uses Modbus TCP as its communication protocol. The ET-M8196F acts as a server in a Modbus TCP network and supports all standard Modbus function codes defined by the Modbus TCP protocol. Nowadays many PCs have got limited PCI slots; therefore the ET-M8196F can be used to replace PCI motion control cards. The ET-M8196F has got two Ethernet ports which allow daisy chaining.

The motion controller of the ET-M8196F consists of an Ethernet communication module and a 6-axis motion control card. A digital signal processor (DSP) is the brain of the motion controller which calculates the commanded move trajectory and manages supervisory control by monitoring the limits and emergency stops to ensure safe operation. I/O control output (e.g. latch, compare, encoder counter etc.) is realized in a Field Programmable Gate Array (FPGA).

The motion controller is suitable for general-purpose motion control applications. In additions to its wide speed range, this intelligent motion controller also has a variety of built-in motion control functions, such as 2- to 6-axis linear interpolation, 2- or 3-axis circular interpolation, helical interpolation, T/S-curve acceleration/deceleration, and automatic home search, etc.

In addition the ET-M8196F acts as an FRnet master and can control up to 128 digital outputs and 128 digital inputs. FRnet is a two-wire serial bus and has a scan interval of 0.72 ms and it is specifically designed for easy and cost effective wiring. ICPDAS provides a large range of FRnet I/O terminal boards and modules.

An application programming interface (API) for communicating with the ET-M8196F motion controller is being provided. This enables the user's program on the host computer to easily interact with the motion controller. A software utility for Ethernet configuration and basic motion settings and execution is part of the software package.



ET-M8196F Interface Functions

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■ Specifications

Specifications				
Model		ET-M8196F		
System Specifications				
Communication		Ethernet		
Communication Protocol		Modbus TCP		
Number of Axes		6 axes		
Motion Control Type		DSP Based		
Pulse Output Rate		4 MPPS (Max.)		
Dulas Outro	CW/CCW	Yes		
Pulse Output Mode	PULSE/DIR	Yes		
	A/B Pulse	Yes		
Command Type		Pulse Command		
	Linear Interpolation	2/6 axes		
Interpolation	Circular Interpolation	2/3 axes		
Trice polation	Helical Interpolation	3 axes		
	Continuous Interpolation	2/3 axes		
Auto-Home Search		Yes		
Manual Pulse Generation		-		
Velocity Profile	Trapezoidal Curve	Yes		
	S-Curve	Yes		
Ring Counter Mode		Yes		
Axis I/O				
	Home	Yes		
Mechanical Switch Input	Near Home	Yes		
	Limit (Positive/Negative)	Yes		
	Emergency	Yes		
	Latch	Yes		
Servo I/O Interface	Input: INP, ALM, RDY	Yes		
	Output: SVON, ALMRST ERC	Yes		
Encoder Interface	A/B Pulse	Yes		
	Up/Down	Yes		
Encoder Counter		32-bit		
Encoder Counting Rate		12 MHz		
Position Compare Trigger		4 MHz		

Model		ET-M8196F		
Digital Input				
Digital Innut Channels	Local	12 DI		
Digital Input Channels	Frnet	Up to 128 DI		
Digital Output				
Digital Output Channels	Local	3 DO		
Digital Output Charineis	FRnet	Up to 128 DO		
Input Signal Filter	Yes			
I/O Isolation (with daughter board)	2500 Vrms optical isolation (with DN-8368)			
Connector	68-pin VHDCI Connector and 20-pin SCSI-II			
Power				
Input Voltage		+24V		
Mechanical				
Dimensions	65x125x121mm			
Environmental				
Operating Temperature	0 ~ +60 °C			
Storage Temperature	-20 ∼ +80 °C			
Operating Humidity				
Storage Humidity	5 ~ 90 % RH, non- condensing			
Software Support				
Windows Driver/DLL/Lib	Windows 7/8/10 32/64 bit: Visual C++ lib/DLL C#, VB.Net DLL Delphi Visual Basic 6.0 BCB 5.0, 6.0 Demo programs			
Software Utility	EzGo Utility			
Macro Programming	-			

Ordering Information

Ethernet Remote Unit with High-speed, DSP-based, 6-axis Motion Control Module

Accessories

DN-8368UB	Photo-isolated Universal Snap-on wiring terminal board	
DN-8368GB	Photo-isolated General-purpose wiring terminal board	
DN-8368MB	Photo-isolated Snap-on wiring terminal board for Mitsubishi MELSERVO-J2 servo amplifier	
DN-20M	General purpose digital input and remote digital I\O (FRnet) extension board	
CA-MINI68-15	68-pin VHDCI to SCSI-II Connector Cable, Length 1.5 M	
CA-SCSI20-M1/M3/M5	20-pin SCSI-II Male connector cable (for Mitsubishi J2 series motor), Length 1 M / 3 M / 5 M.	
CA-26-MJ3-15/30/50(B)	26-pin HD D-Sub Male Cable for Mitsubishi Servo Amplifier, 1.5/3/5 M. (for MELSERVO-J3/J4Series)	
CA-26-PA4-15/30/50(B)	26-pin HD D-Sub Male Cable for Panasonic Servo Amplifier, 1.5/3/5 M. (for MINAS A4/A5 Series)	
CA-26-YSV-15/30/50(B)	26-pin HD D-Sub Male Cable for Yaskawa Servo Amplifier, 1.5/3/5 M. (for Sigma II/III/V Series)	
CA-26-DAA2-15/30/50(B)	26-pin HD D-Sub Male Cable for Delta A2 Servo Amplifier, 1.5/3/5 M. (for ASDA-A2 Series)	
CA-26-DAB2-15/30/50(B)	26-pin HD D-Sub Male Cable for Delta B2 Servo Amplifier, 1.5/3/5 M. (for ASDA-B2 Series)	
CA-26-FFW-15/30/50	26-pin HD D-Sub Male Cable for Fuji Servo Amplifier, 1.5/3/5 M. (for FALDIC-W and ALPHA5 Smart Series)	
CA-26-TTA-15/30/50	26-pin HD D-Sub Male Cable for Teco Servo Amplifier, 1.5/3/5 M. (for TSTA-A/A+ Series)	

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