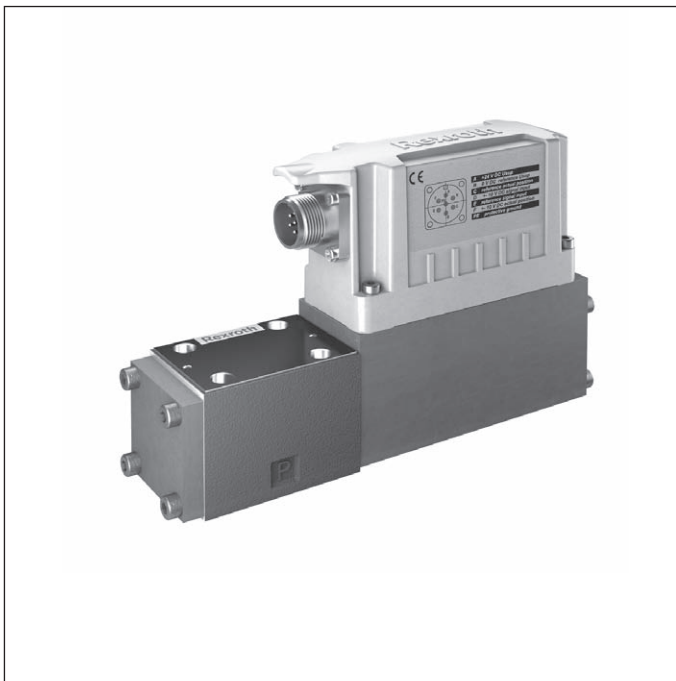


4/4 directional control valves, direct operated,  
with electrical position feedback and integrated  
electronics (OBE)

Type 4WRPEH

**RE 29121**  
www.hydrootvet.ru



- ▶ Size 6
- ▶ Component series 3X
- ▶ Maximum operating pressure 350 bar
- ▶ Rated flow 4...40 l/min ( $\Delta p = 70$  bar)



## Features

- ▶ Reliable - proven and robust design
- ▶ Safe - fail-safe position of the control spool in switched-off condition
- ▶ Energy-efficient - no pilot oil demand
- ▶ High quality - control spool and sleeve in servo quality
- ▶ Flexible - suitable for position, velocity and pressure control
- ▶ Precise - high response sensitivity and little hysteresis

## Contents

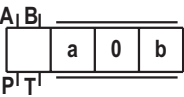



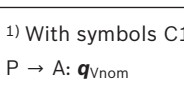
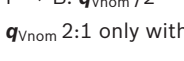
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### Ordering code

01	02	03	04	05	06	07	08	09	10	11	12	13	14	
<b>4</b>	<b>WRP</b>	<b>E</b>	<b>H</b>	<b>6</b>		<b>B</b>			<b>-</b>	<b>3X</b>	<b>/</b>	<b>/</b>	<b>24</b>	<b>*</b>

01	4 main ports	<b>4</b>
02	High-response valve, direct operated	<b>WRP</b>
03	With integrated electronics	<b>E</b>
04	Control spool/sleeve	<b>H</b>
05	Size 6	<b>6</b>

### Control spool symbols

06	Symbol	Flow characteristics L	Flow characteristics P	
				
		●	●	<b>C</b>
		●	●	<b>C1</b> <sup>1)</sup>
		●	●	<b>C4</b>
		●	●	<b>C3</b>
		●	●	<b>C5</b> <sup>1)</sup>
	<sup>1)</sup> With symbols C1 and C5: P → A: $q_{Vnom}$ B → T: $q_{Vnom} / 2$ P → B: $q_{Vnom} / 2$ A → T: $q_{Vnom}$ $q_{Vnom}$ 2:1 only with rated flow = 40 l/min			

07	Installation side of the inductive position transducer	<b>B</b>
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### Rated flow of size 6 with 70 bar valve pressure differential (35 bar/control edge)

08		Flow characteristics L	Flow characteristics P	
	04 l/min	●	● (inflection at 40 %)	<b>04</b>
	12 l/min	●		<b>12</b>
	15 l/min		● (inflection at 60 %)	<b>15</b>
	24 l/min	●		<b>24</b>
	25 l/min		● (inflection at 60 %)	<b>25</b>
	40 l/min	●	● (inflection at 40 %)	<b>40</b>

● = Delivery range

### Flow characteristics

09	Linear	<b>L</b>
	Inflected characteristic curve, linear	<b>P</b>

10	Component series 30 ... 39 (30 ... 39: Unchanged installation and connection dimensions)	<b>3X</b>
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### Seal material

11	NBR seals	<b>M</b>
	FKM seals	<b>V</b>

### Ordering code

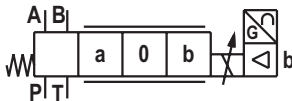
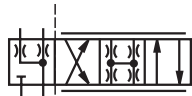
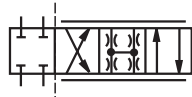
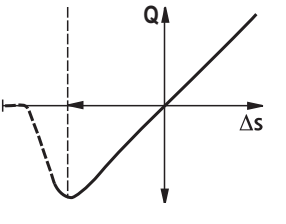
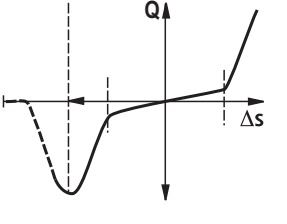
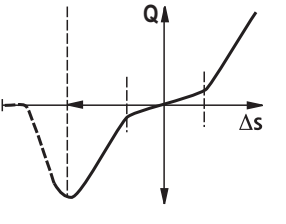

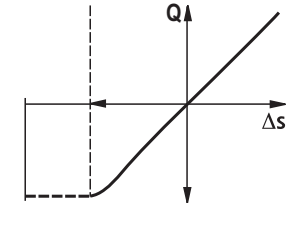
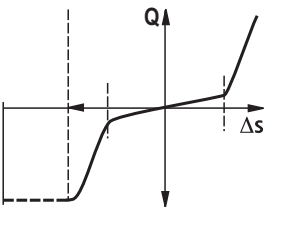
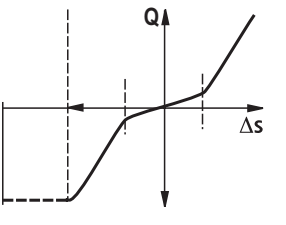
01	02	03	04	05	06	07	08	09	10	11	12	13	14	
<b>4</b>	<b>WRP</b>	<b>E</b>	<b>H</b>	<b>6</b>		<b>B</b>			<b>-</b>	<b>3X</b>	<b>/</b>	<b>/</b>	<b>24</b>	<b>*</b>

12	Supply voltage of the integrated electronics: 24 VDC	<b>24</b>
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### Interfaces of the control electronics

13	Command value input ±10 V	<b>A1</b>
	Command value input 4 ... 20 mA	<b>F1</b>
14	Further details in the plain text	

### Symbols

	Linear	P: Inflection 60 % [ $q_{Vnom} = 15.25$ l/min]	P: Inflection 40 %
 C3, C5   C4, C1			
 C			
Standard = 1:1, $q_{Vnom}$ 2:1 only with rated flow = 40 l/min			

## Function, section

### Set-up

The 4WRPEH high-response valve mainly consists of:

- ▶ Valve housing with control spool and sleeve in servo quality (1)
- ▶ Control solenoid with position transducer (2)
- ▶ On-board electronics (OBE) (3) with analog interface (4)

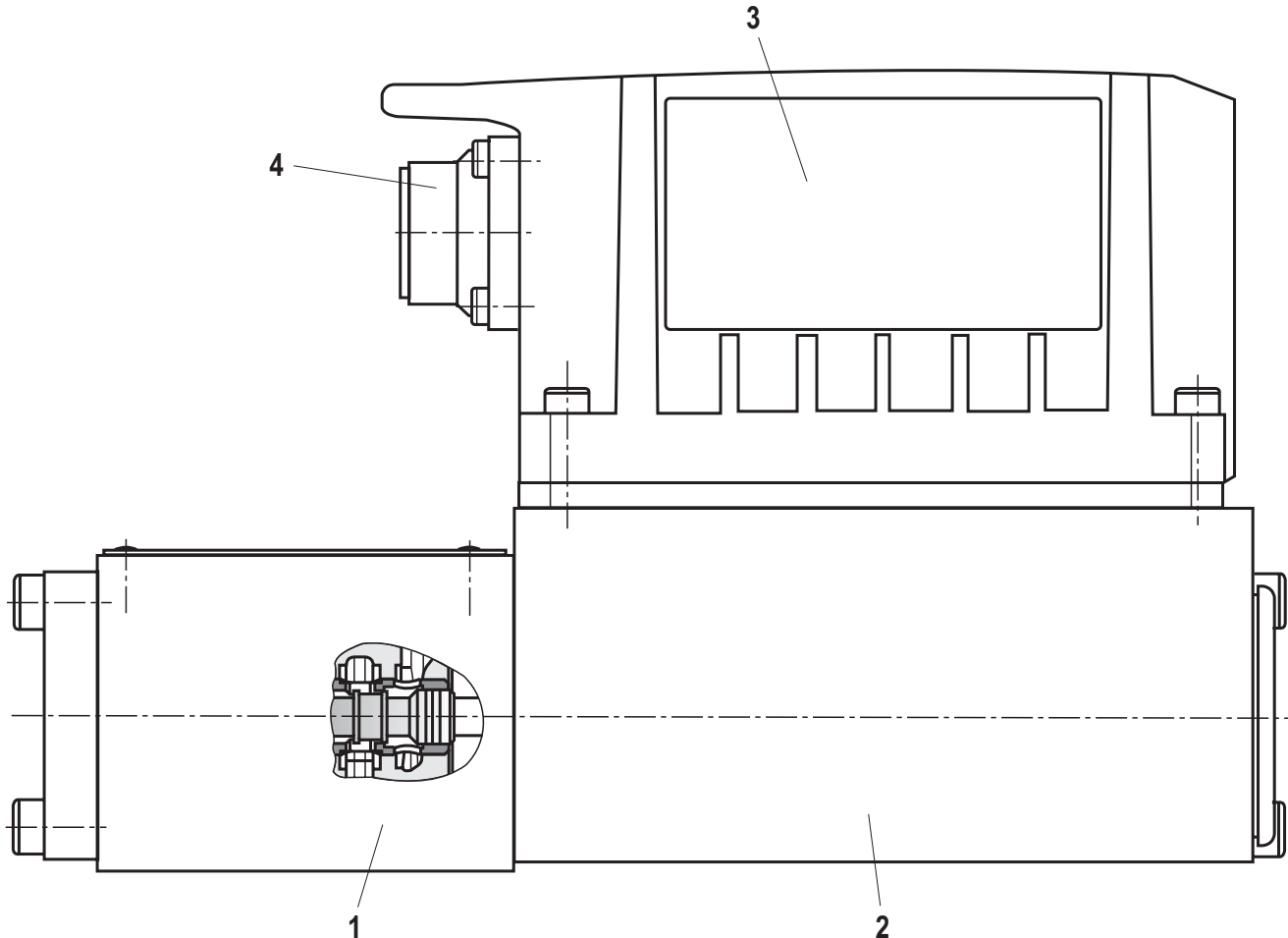
### Failure of supply voltage

If the supply voltage fails or if the minimum supply voltage is no longer achieved as well as in case of cable break, the integrated electronics will de-energize the control solenoid, the control spool will take the fail-safe position.

### Functional description

The 4WRPEH is a direct operated directional control valve with electrical position feedback and integrated electronics (OBE). The integrated electronics (OBE) compares the specified command value to the actual position value.

In case of control deviations, the stroke solenoid will be activated. Due to the changed magnetic force, the control spool is adjusted against the spring. Stroke/control spool cross-section is controlled proportionally to the command value. In case of a command value presetting of 0 V, the electronics adjusts the control spool against the spring to central position. In deactivated condition, the spring is untensioned to a maximum and the valve is in fail-safe position.



## Technical data

(For applications outside these parameters, please consult us!)

general	
Design	Spool valve, direct operated, with steel sleeve
Actuation	Proportional solenoid with position control, OBE
Type of connection	Subplate mounting, porting pattern according to ISO 4401
Installation position	Any
Ambient temperature range	°C -20 ... +60
Storage temperature range with UV protection	°C +10 ... +40
Transport temperature	°C -30 ... +80
Sine test according to DIN EN 60068-2-6	10...2000 Hz / maximum of 10 g / 10 cycles / 3 axes
Noise test according to DIN EN 60068-2-64	20...2000 Hz / 10 g <sub>RMS</sub> / 30 g peak / 30 min / 3 axes
Transport shock according to DIN EN 60068-2-27	15g / 11 ms / 3 axes
Weight	kg 2.9
Maximum relative humidity (no condensation)	% 95
Maximum solenoid surface temperature	°C 150
MTTFd value according to EN ISO 13849	Years 150 (for further details see data sheet 08012)

hydraulic	
Hydraulic fluid	See table on page 6
Viscosity range	- recommended mm <sup>2</sup> /s 20 ... 100
	- maximum admissible mm <sup>2</sup> /s 10 ... 800
Hydraulic fluid temperature range (flown-through)	°C -20 ... +70
Maximum admissible degree of contamination of the hydraulic fluid, cleanliness class according to ISO 4406 (c)	Class 18/16/13 <sup>1)</sup>

Rated flow at $\Delta p = 35$ bar per edge <sup>2)</sup>	l/min	4	12	15	24/25	40
Maximum operating pressure	- Ports A, B, P bar	350				
	- Port T bar	250				
Limitation of use with regard to the transition to failsafe (values apply to summed edge)	- Spool symbols C3, C5, C bar	350	350	350	350	160
	- Spool symbols C1, C4 bar	350	350	280	250	100
Leakage flow at 100 bar	- Linear characteristic curve L cm <sup>3</sup> /min	< 180	< 300	-	< 500	< 900
	- Inflected characteristic curve P cm <sup>3</sup> /min	< 150	-	< 180	< 300	< 450

static/dynamic	
Hysteresis	% < 0.1
Range of inversion	% < 0.05
Response sensitivity	% < 0.05
Manufacturing tolerance $q_{Vmax}$	% < 10
Temperature drift (temperature range 20 °C ... 80 °C)	Zero shift < 0.25 % with $\Delta\theta = 10$ K
Pressure drift	%/100 bar Zero shift < 0.15
Zero compensation	Ex factory $\pm 1$ %

<sup>1)</sup> The cleanliness classes specified for the components must be adhered to in hydraulic systems. Effective filtration prevents faults and at the same time increases the life cycle of the components.

For the selection of the filters see [www.boschrexroth.com/filter](http://www.boschrexroth.com/filter).


<sup>2)</sup> Flow with different  $\Delta p$ :

$$q_x = q_{Vnom} \cdot \sqrt{\frac{\Delta p_x}{35}}$$

**Technical data**

(For applications outside these parameters, please consult us!)

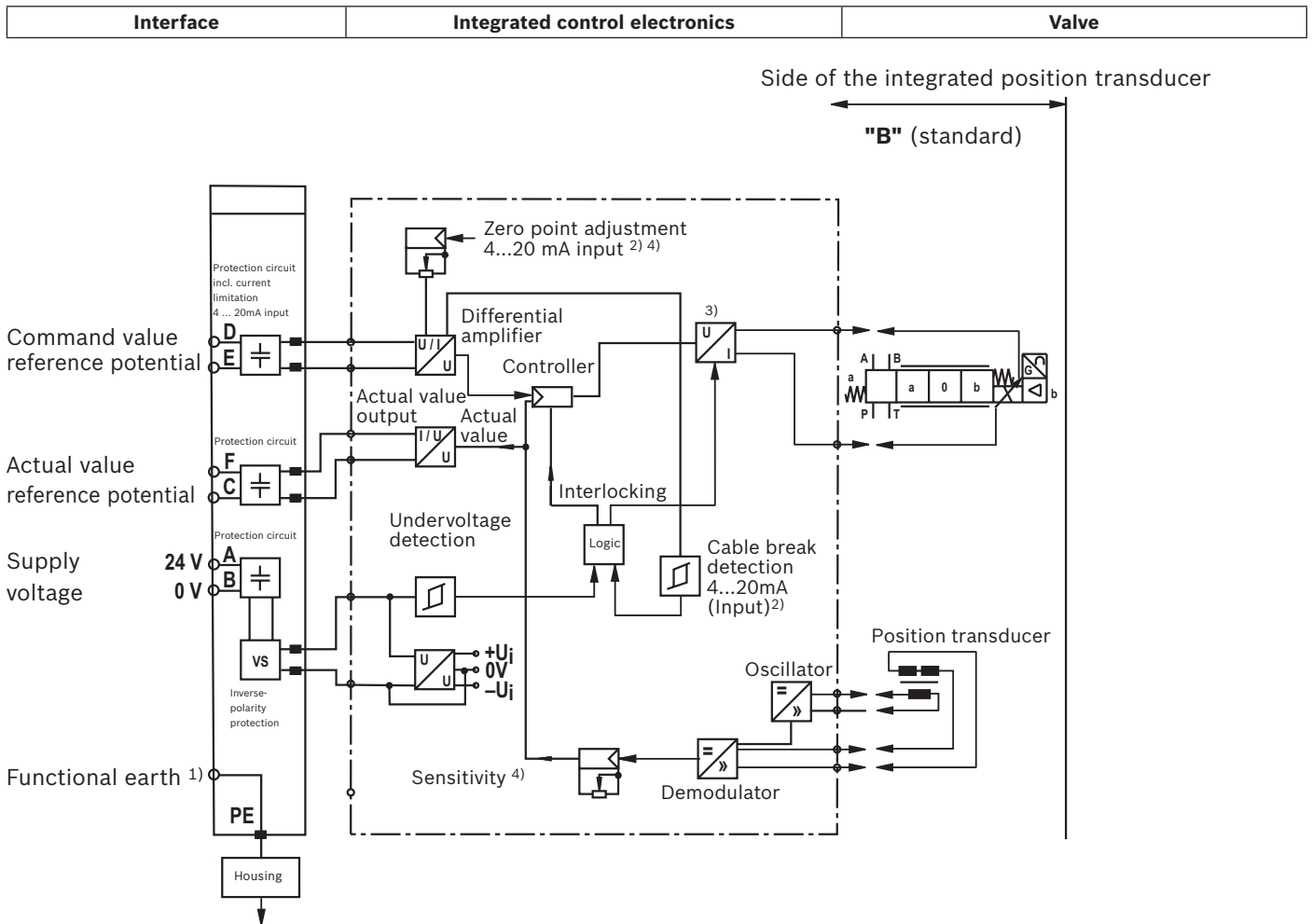
Hydraulic fluid	Classification	Suitable sealing materials	Standards
Mineral oils and related hydrocarbons	HL, HLP, HLPD, HVL, HVLDP	NBR, FKM	DIN 51524
Bio-degradable – insoluble in water	HETG	NBR, FKM	ISO 15380
	HEES	FKM	
– soluble in water	HEPG	FKM	ISO 15380
Flame-resistant – water-free	HFDU, HFDR	FKM	ISO 12922
	HFC (Fuchs HYDROTHERM 46M, Petrofer Ultra Safe 620)	NBR	ISO 12922

 **Important information on hydraulic fluids!**

- ▶ There may be limitations regarding the technical valve data (temperature, pressure range, life cycle, maintenance intervals, etc.)!
- ▶ The flash point of the hydraulic fluid used must be 40 K higher than the maximum solenoid surface temperature.
- ▶ **Mineral oils and related hydrocarbons:**
  - If mineral oils and related hydrocarbons are used, data sheet 90220 must be complied with!
- ▶ **Bio-degradable:**
  - If bio-degradable hydraulic fluids are used, data sheet 90221 must be complied with!
- ▶ **Flame-resistant – water-free:**
  - If flame-resistant, water-free hydraulic fluids are used, data sheet 90222 must be complied with!
- ▶ **Flame-resistant – containing water:** The maximum pressure differential per control edge is 50 bar. Pressure pre-loading at the tank port > 20 % of the pressure differential; otherwise, increased cavitation. Life cycle as compared to operation with mineral oil HL, HLP 50 % to 100 %.

electrical, integrated electronics (OBE)	
Relative duty cycle (%)	100 (continuous operation)
Protection class according to EN 60529	IP 65 with mounted and locked plug-in connectors
Supply voltage	24 V=
Terminal A:	At least 19 V=/maximum 36 V=
Terminal B:	0 V
Maximum admissible residual ripple	2.5 Vpp
Maximum power consumption	40 VA
Fuse protection, external	2.5 A <sub>T</sub>
Input, version <b>A1</b>	Differential amplifier, $R_i = 100 \text{ k}\Omega$
Terminal D: $U_E$	0 ... $\pm 10 \text{ V}$
Terminal E:	0 V
Input, version <b>F1</b>	Load, $R_{sh} = 200 \Omega$
Terminal D: $I_{D-E}$	4 ... (12) ... 20 mA
Terminal E: $I_{D-E}$	Current loop $I_{D-E}$ feedback
Maximum voltage of the differential inputs against 0 V	D → B } Maximum 18 V E → B }
Test signal, version <b>A1</b>	LVDT
Terminal F: $U_{test}$	0 ... $\pm 10 \text{ V}$
Terminal C:	Reference 0 V
Test signal, version <b>F1</b>	LVDT signal 4 ... 20 mA at external load 200 ... 500 $\Omega$ maximum
Terminal F: $I_{F-C}$	4 ... 20 mA output
Terminal C: $I_{F-C}$	Current loop $I_{F-C}$ feedback
Functional earth and screening	See pin assignment (CE-compliant installation)
Adjustment	Calibrated in the factory, see valve characteristic curve
Conformity	CE according to EMC Directive 2004/108/EC Tested according to EN 61000-6-2 and EN 61000-6-3

### Block diagram/controller function block

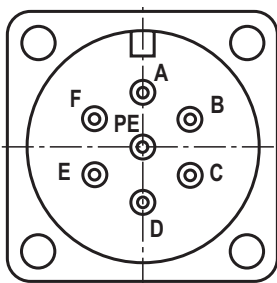


- 1) PE port is connected to the valve housing
- 2) Applies only to F1 interface
- 3) Output stage current-controlled
- 4) Calibrated in the factory

### Electrical connections and assignment

#### Connector pin assignment

Pin	Signal	Assignment interface A1	Assignment interface F1
A	Supply voltage	24 VDC	
B		0 V	
C	Reference potential actual value	Reference potential actual value - pin F	
D	Differential amplifier input	Command value ±10 V	Command value 4 to 20 mA
E		Reference potential command value - pin D	
F	Measuring output (actual value)	Actual value ±10 V	Actual value 4 to 20 mA
PE		Functional earth (directly connected to the valve housing)	



**Command value:** Positive command value (0 to 10 V or 12 to 20 mA) at D and reference potential at E result in flow from P → A and B → T.  
 Negative command value (0 to -10 V or 12 to 4 mA) at D and reference potential at E result in flow from P → B and A → T.

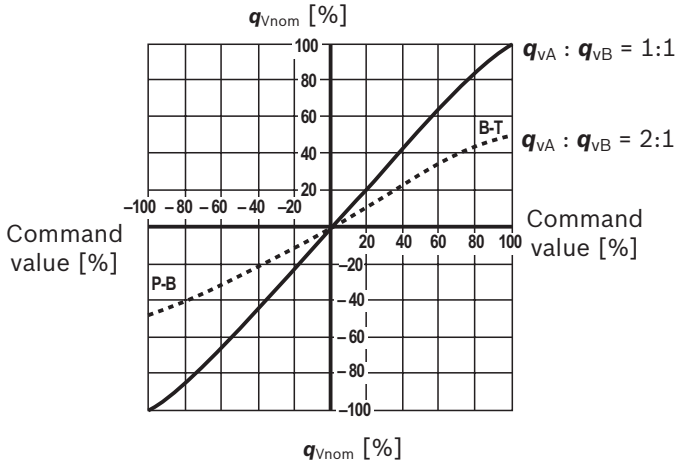
**Connection cables:** Recommendation: – up to 20 m cable length type LiYCY 7 x 0.75 mm<sup>2</sup>  
 – up to 40 m cable length type LiYCY 7 x 1.0 mm<sup>2</sup>  
 Only connect the screening to PE on the supply side.

**Characteristic curves**

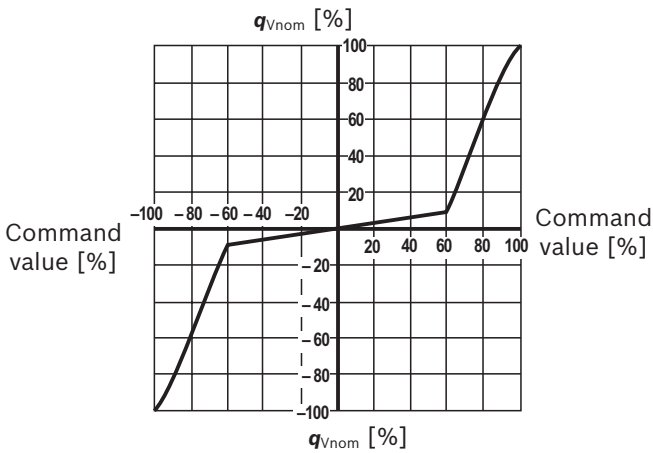
(measured with HLP46,  $\vartheta_{oil} = 40 \pm 5 \text{ }^\circ\text{C}$ )

**Flow/signal function**

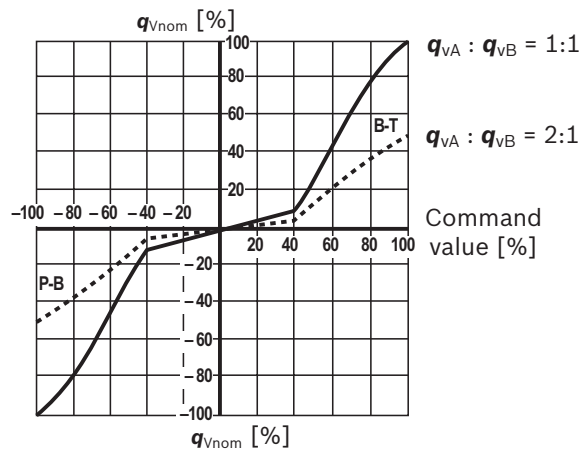
**L: Linear**



**P: Inflection 60 %**



**P: Inflection 40 %**



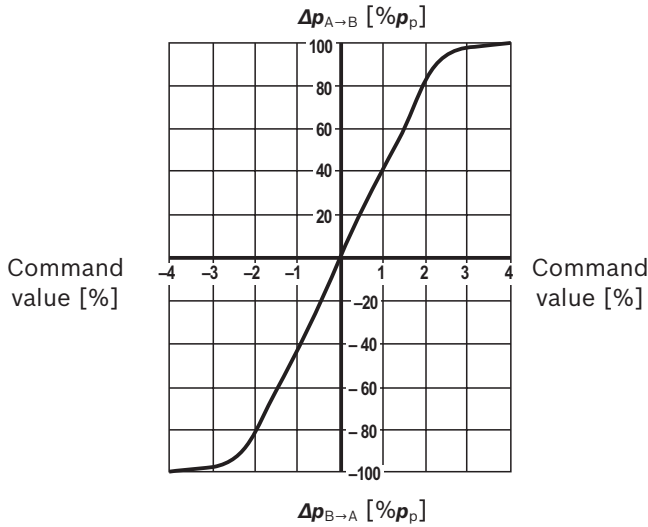
	Fail-safe position			
C3, C5		Leakage flow at	100 bar	P → A 50 cm <sup>3</sup> /min P → B 70 cm <sup>3</sup> /min
		Flow at	$\Delta p = 35 \text{ bar}$	A → T 10 ... 20 l/min B → T 7 ... 20 l/min
C4, C1		Leakage flow at	100 bar	P → A 50 cm <sup>3</sup> /min P → B 70 cm <sup>3</sup> /min
				A → T 70 cm <sup>3</sup> /min B → T 50 cm <sup>3</sup> /min
	Fail-safe	$p = 0 \text{ bar} \Rightarrow 7 \text{ ms}$ $p = 100 \text{ bar} \Rightarrow 10 \text{ ms}$	Internal shut-off in case of error $U_B \leq 17.5 \text{ V}$ and/or $I \leq 2 \text{ mA}$	



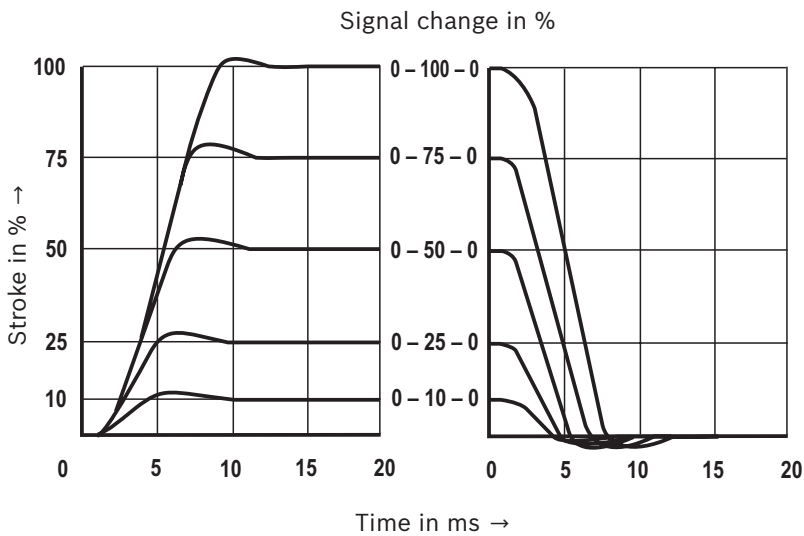
### Characteristic curves

(measured with HLP46,  $\vartheta_{oil} = 40 \pm 5 \text{ }^\circ\text{C}$ )

#### Pressure/signal characteristic curve



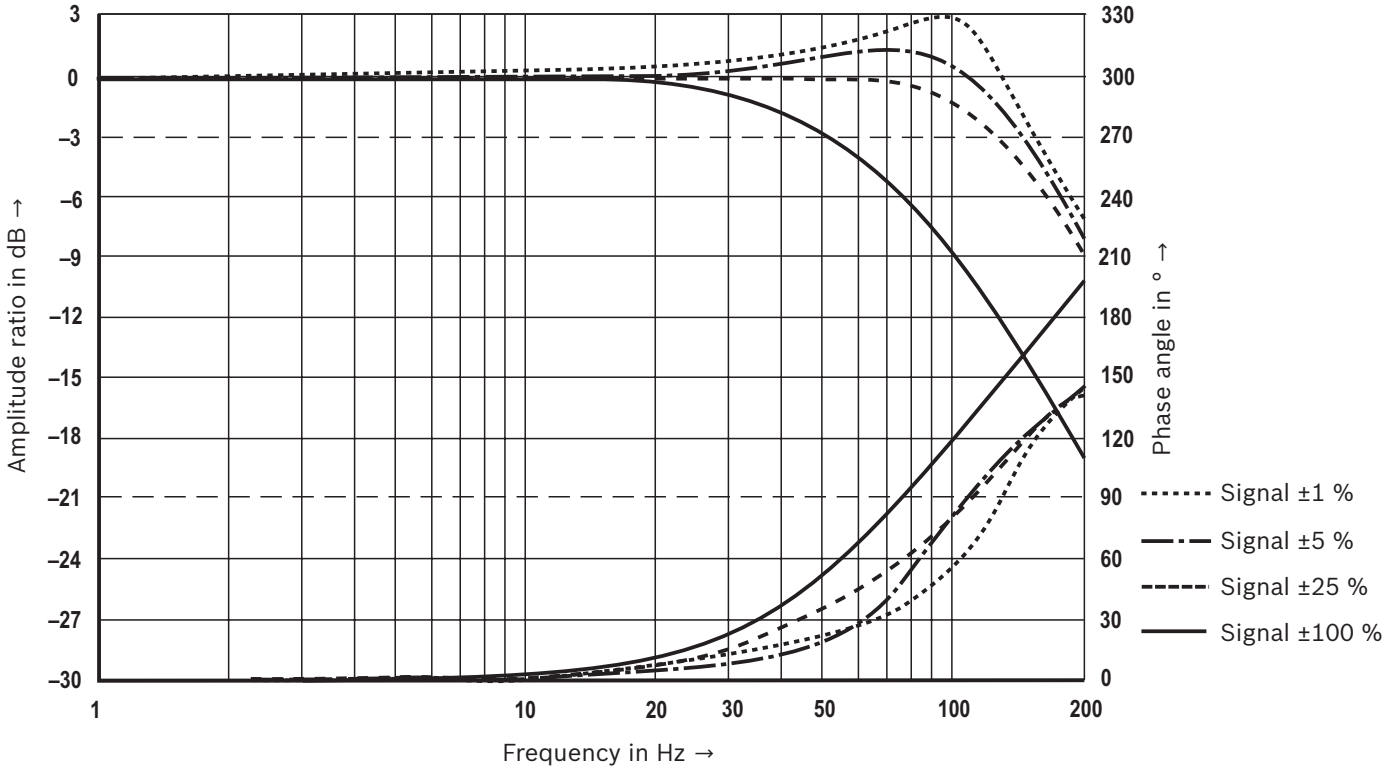
#### Transition function with stepped electric input signals



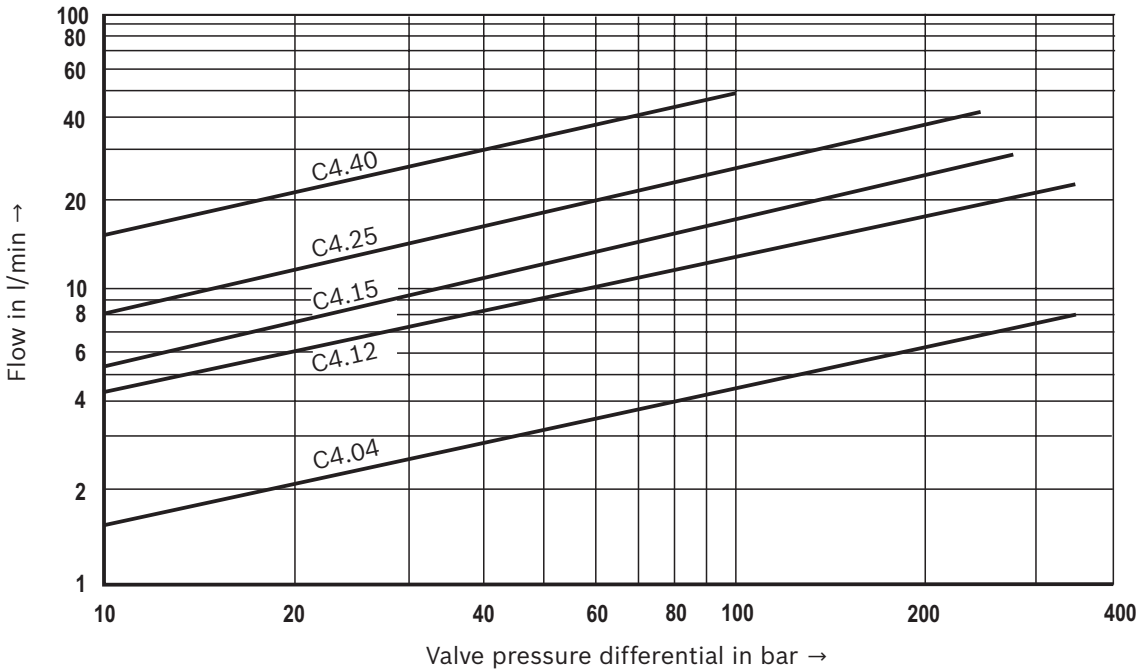
**Characteristic curves**

(measured with HLP46,  $\vartheta_{oil} = 40 \pm 5 \text{ }^\circ\text{C}$ )

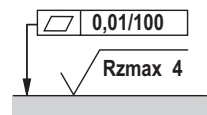
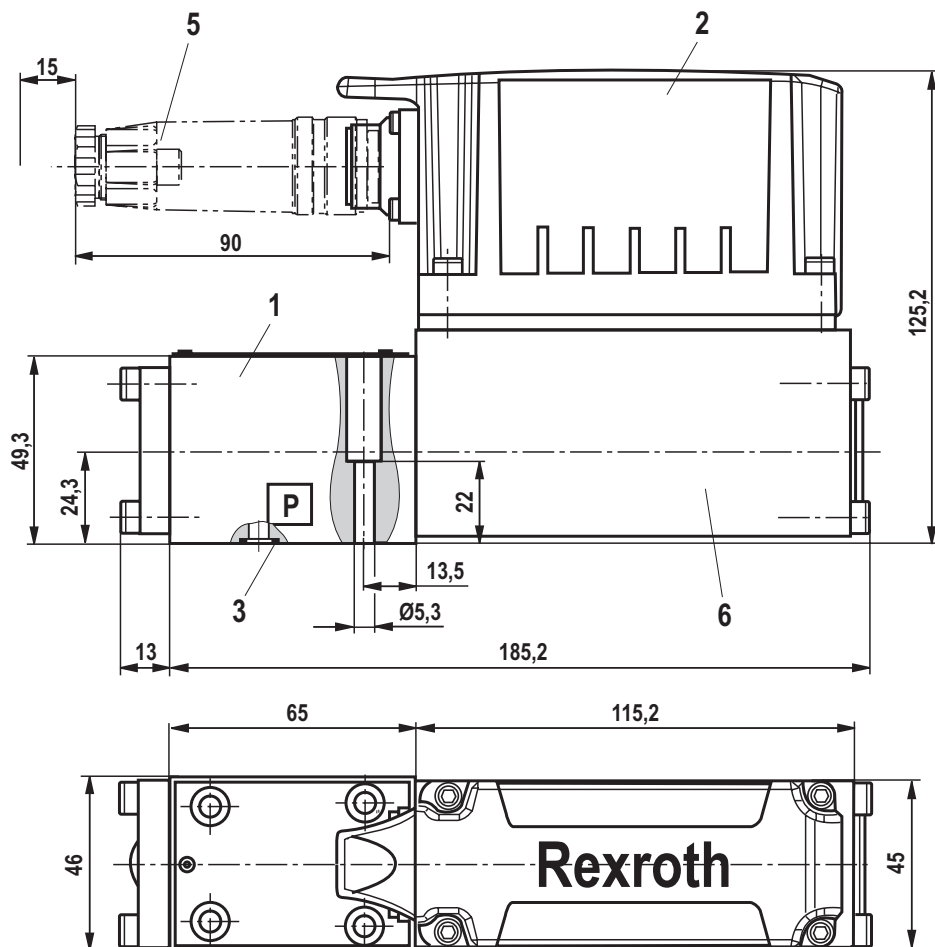
**Frequency response characteristic curves**



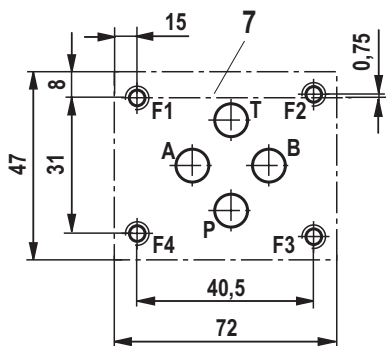
**Flow/load function with maximum valve opening**



**Dimensions** (dimensions in mm)



Required surface quality of the valve contact surface



- 1 Valve housing
- 2 Integrated electronics
- 3 O-rings  $\text{Ø} 9.25 \times 1.78$  (ports P, A, B, T)
- 4 Mating connector not included in the scope of delivery, see data sheet 08008 (separate order)
- 5 Space required to remove the mating connector
- 6 Control solenoid with position transducer
- 7 Machined valve contact surface, porting pattern according to ISO 4401-03-02-0-05  
Deviating from the standard:  
Ports P, A, B, T  $\text{Ø} 8 \text{ mm}$   
Minimum screw-in depth: Ferrous metal  $1.5 \times \text{Ø}$   
Non-ferrous  $2 \times \text{Ø}$

**Notice!**  
The dimensions are nominal dimensions which are subject to tolerances.

## Dimensions

Hexagon socket head cap screws		Material number
Size 6	4x ISO 4762 - M5 x 30 - 10.9-flZn-240h-L Tightening torque $M_A = 7 \text{ Nm} \pm 10 \%$ or 4x ISO 4762 - M5 x 30 - 10.9 Tightening torque $M_A = 8.9 \text{ Nm} \pm 10 \%$	R913000316

**Notice:** The tightening torque of the hexagon socket head cap screws refers to maximum operating pressure.

Subplates	Data sheet	Material number
Size 6	45052	

## Accessories (not included in the scope of delivery)

Mating connectors	Data sheet	Material number
Mating connector for high-response valve DIN EN 175201-804	08006	e.g. R900021267 (plastic) e.g. R900223890 (metal)

Test and service devices	Data sheet	Material number
Service case with test device for proportional servo valves with integrated electronics (OBE)	29685	

## Project planning / maintenance instructions / additional information

- ▶ General operating instructions: Hydraulic valves for industrial applications, see data sheet 07600-B
- ▶ Assembly, commissioning and maintenance of hydraulic systems, see data sheet 07900
- ▶ Assembly, commissioning and maintenance of servo valves and high-response valves, see data sheet 07700
- ▶ Assembly, commissioning and maintenance of proportional valves, see data sheet 07800

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